

CS5371

Theory of Computation

Lecture 11: Computability Theory II
(TM Variants, Church-Turing Thesis)

Objectives

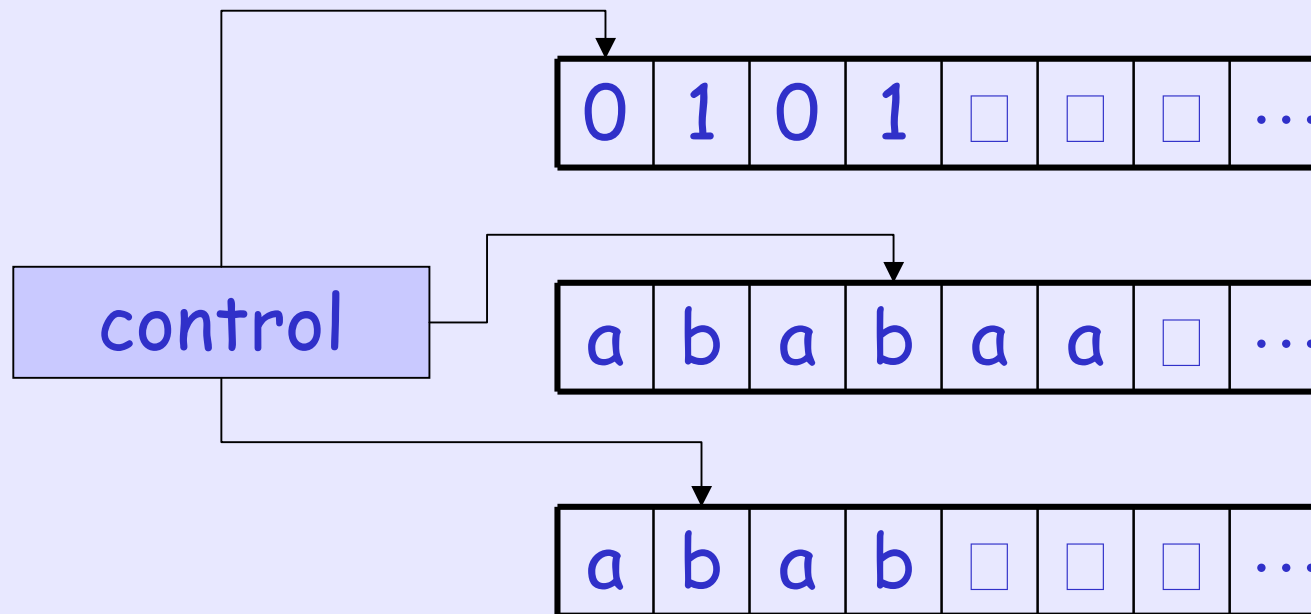
- Variants of Turing Machine
 - With Multiple Tapes
 - With Non-deterministic Choice
 - With a Printer
- Introduce Church-Turing Thesis
 - Definition of Algorithm

Variants of TM

- Similar to the original TM
- One example: TM such that the tape head can move left, right, or stay
 - the class of languages that are recognized by this new kind of TM = the class of languages that are recognized by original TM (Why?)
- There are more variants...

Variant 1: Multi-Tape TM

□ = blank symbols



It is like a TM, but with several tapes

Multi-tape TM (2)

- Initially, the input is written on the first tape, and all other tapes blank
- The transition function of a k -tape TM has the form

$$\delta : Q \times \Gamma^k \rightarrow Q \times \Gamma^k \times \{L, R, S\}^k$$

- Obviously, given a TM, we can find a k -tape TM that recognizes the same language
- How about the converse?

Multi-tape TM = one-tape TM

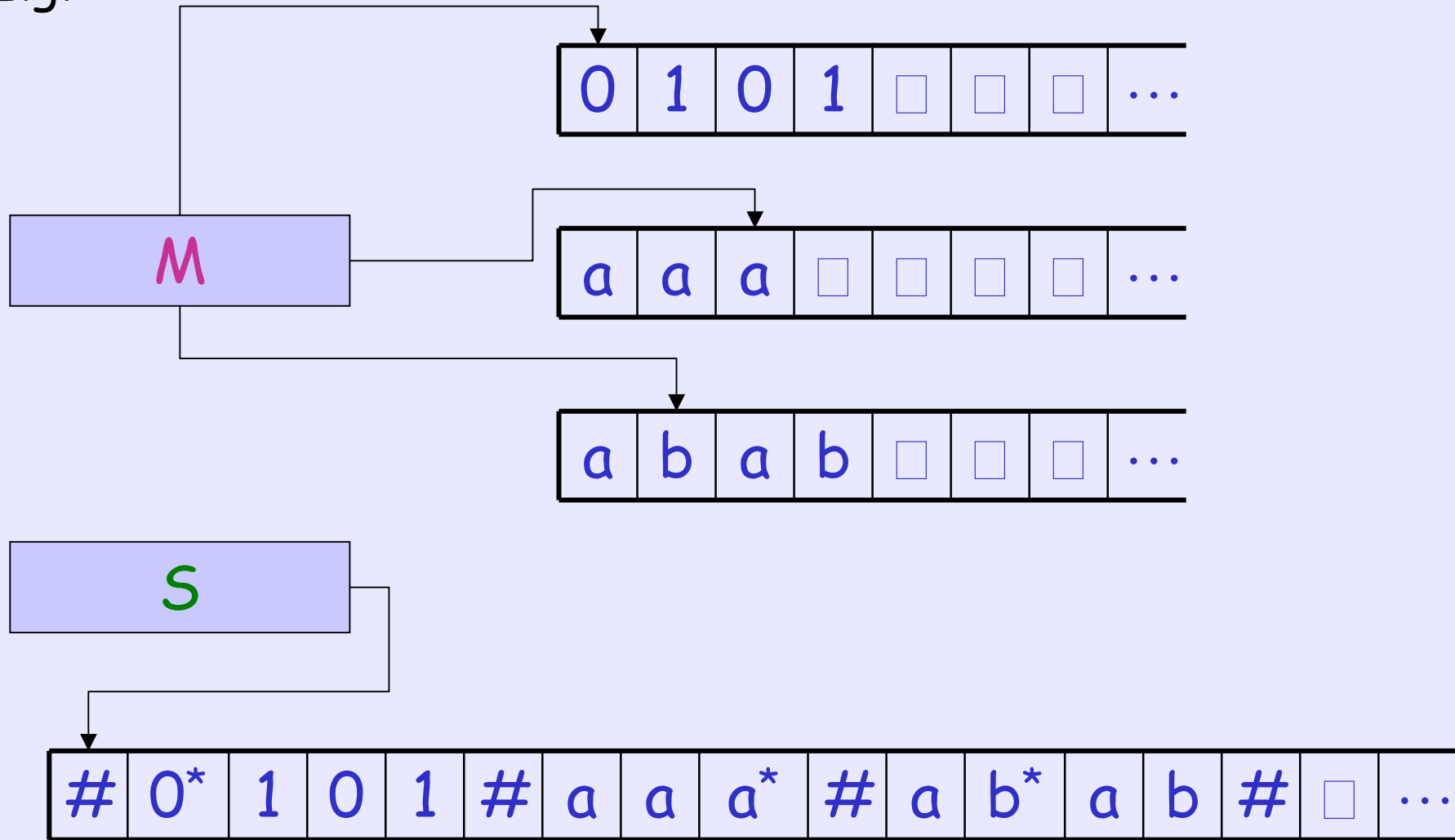
Theorem: Given a k -tape TM, we can find an equivalent TM (that is, a TM that recognizes the same language).

Proof: Let M be the k -tape TM (with multiple tape). We show how to convert M into some TM S (with single tape).

Multi-tape TM = one-tape TM

1. To simulate k tapes, S separates the contents of different tapes by $\#$
 2. To simulate the tape heads, S marks the symbol under each tape head with a star (The starred symbols are just new symbols in the tape alphabet of S)
- We can now think of the tape of S to be containing k "virtual" tapes and their tape heads

E.g.



Note: $\Gamma_M = \{0, 1, a, b, \square\}$ and $\Gamma_S = \{0, 1, a, b, \square, \#, 0^*, 1^*, a^*, b^*, \square^*, \#\}$

The Simulation

On input $w = w_1w_2\dots w_n$

Step 1. S stores in the tape

$\# w_1^* w_2^* \dots w_n^* \# \square^* \# \square^* \# \dots \#$

Step 2. S scans from the first $\#$ to the $(k+1)^{\text{st}}$ $\#$ to find out what symbols are under each virtual tape head

Then, S goes back to the first $\#$ and updates the virtual tapes according to what M 's transition function will do

Step 3. If M accepts, accept w ; If M rejects, reject w ; Else, repeat Step 2

More on the Simulation

After the transition, the virtual tape head may be on top of the # symbol. **Questions:**

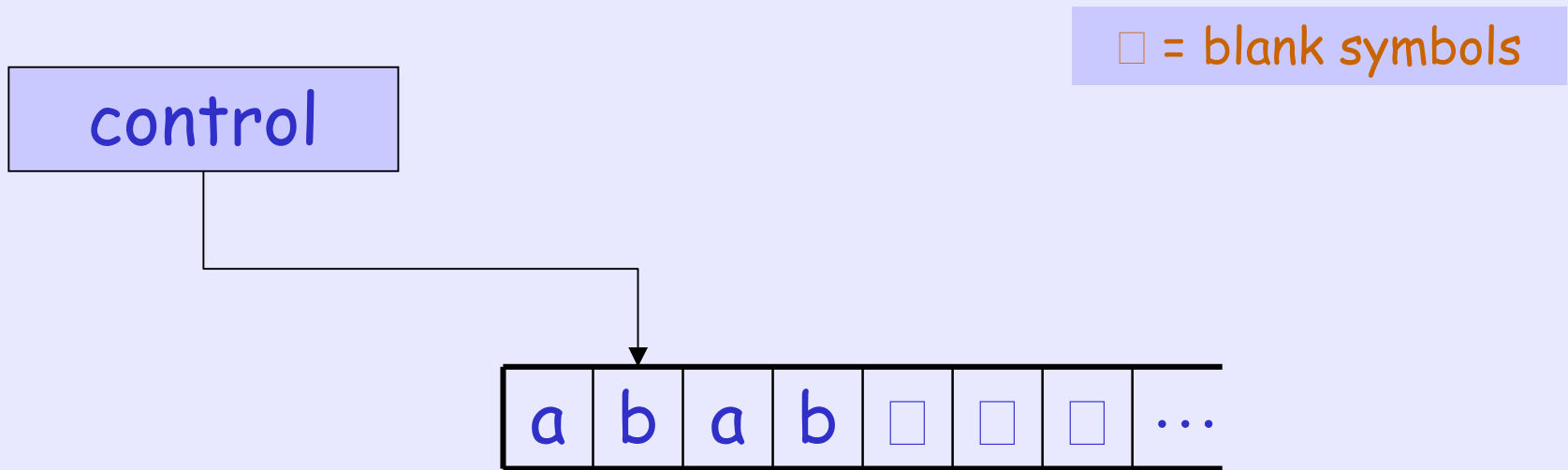
(1) What do we know? (2) What should we do?

Answer:

(1) The tape head of the virtual tape has moved to the unread blank portion of the virtual tape

(2) In this case, we overwrite # by \square^* , shifts the tape contents of S from this cell (i.e., #) to the rightmost #, one unit to the right. After that, comes back and continues the simulation

Variant 2: NTM



It is like a TM, but with non-deterministic control

Computation of NTM

- The transition function of NTM has the form

$$\delta : Q \times \Gamma \rightarrow 2^{Q \times \Gamma \times \{L, R\}}$$

- For an input w , we can describe all possible computations of NTM by a **computation tree**, where

root = start configuration,

children of node C = all configurations that can be yielded by C

- The NTM **accepts** the input w if **some** branch of computation (i.e., a path from root to some node) leads to the accept state

NTM = TM

Theorem: Given an NTM that recognizes a language L , we can find a TM that recognizes the same language L .

Proof: Let N be the NTM. We show how to convert N into some TM D . The idea is to simulate N by trying all possible branches of N 's computation. If one branch leads to an accept state, D accepts. Otherwise, D 's simulation will not terminate.

NTM = TM (Proof)

- To simulate the search, we use a 3-tape TM for D
 - first tape stores the input string
 - second tape is a working memory, and
 - third tape "encodes" which branch to search
- What is the meaning of "encode"?

NTM = TM (Proof)

- Let $b = |Q \times \Gamma \times \{L, R\}|$, which is the maximum number of children of a node in N 's computation tree.
- We encode a branch in the tree by a string over the alphabet $\{1, 2, \dots, b\}$.
 - E.g., 231 represents the branch:
root $r \rightarrow r$'s 2nd child $c \rightarrow$
 c 's 3rd child $d \rightarrow d$'s 1st child

NTM = TM (Proof)

On input string w ,

Step 1. D stores w in Tape 1 and \square in Tape 3

Step 2. Repeat

2a. Copy Tape 1 to Tape 2

2b. Simulate N using Tape 2, with the branch of computation specified in Tape 3.

Precisely, in each step, D checks the next symbol in Tape 3 to decide which choice to make. (Special case ...)

NTM = TM (Proof)

2b [Special Case].

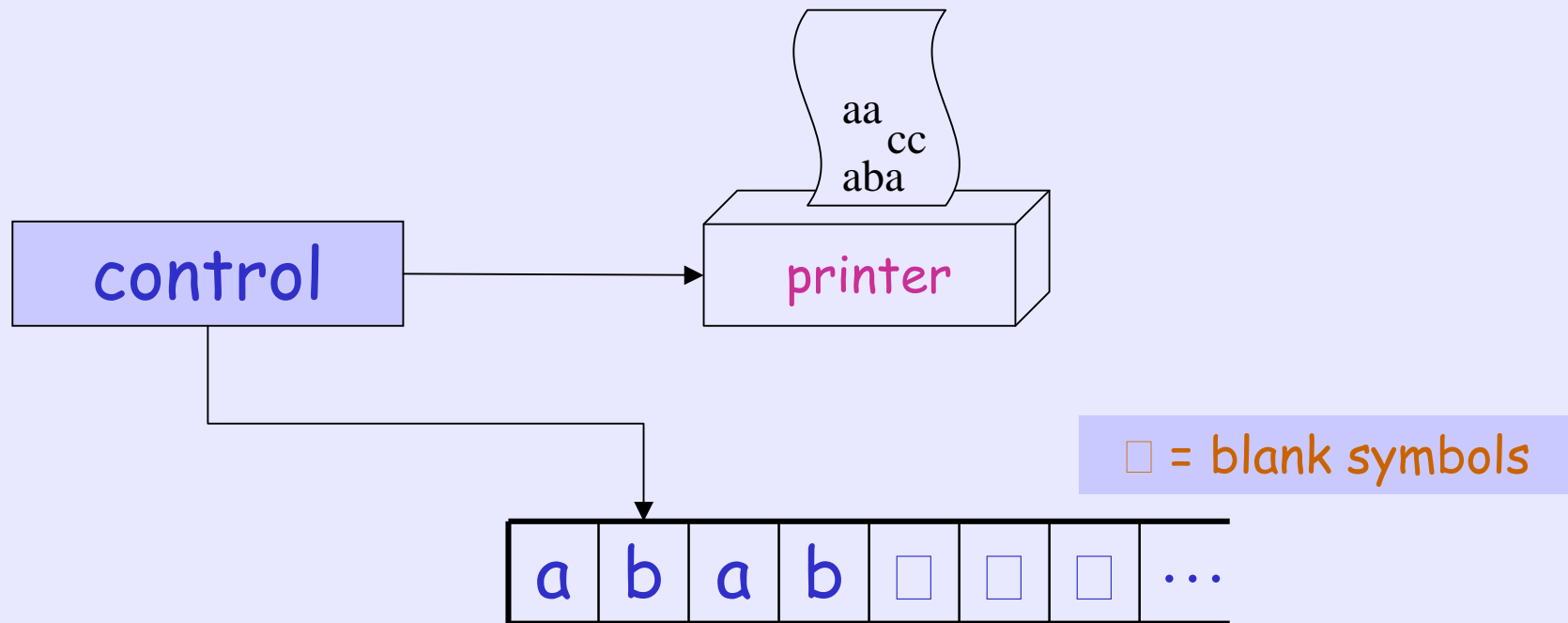
1. If this branch of **N** enters accept state, accepts **w**
2. If no more chars in Tape 3, or a choice is invalid, or if this branch of **N** enters reject state, **D** aborts this branch

2c. Copy Tape 1 to Tape 2, and update Tape 3 to store the next branch (in Breadth-First Search order)

NTM = TM (Proof)

- In the simulation, **D** will first examine the branch ε (i.e., root only), then the branch 1 (i.e., root and 1st child only), then the branch 2, and then 3, 4, ..., b , then the branches 11, 12, 13, ..., 1 b , then 21, 22, 23, ..., 2 b , and so on, until the examined branch of **N** enters an accept state (what if **N** enters a reject state?)
- If **N** does not accept w , the simulation of **D** will run forever
- Note that we cannot use **DFS** (depth-first search) instead of **BFS** (why?)

Variant 3: Enumerator



It is like a TM, but with a printer

Enumerator (2)

- An enumerator E starts with a blank input tape
- Whenever the TM wants to print something, it sends the string to the printer
- If the enumerator does not halt, it may print an infinite list of strings
- The **language** of E = the set of strings that are (eventually) printed by E
 - Note: E may generate strings in any order, and with repetitions

Enumerator (3)

Theorem: Let L be a language.

- (1) If L is enumerated by some enumerator, there is a TM that recognizes L .
- (2) If L is recognized by some TM, there is an enumerator that enumerates L .

Enumerator (4)

Proof of (1): Let E be the enumerator that enumerates L . Consider the following TM M :

M = On input w :

Step 1. Run E . Whenever E wants to print, compare the string with w .

If they are the same, accept w .

Otherwise, continue to run E .

Thus, M accepts exactly the strings in L

→ there is a TM that recognizes L

Enumerator (5)

Proof of (2): Let M be the TM that recognizes L .
Consider the following enumerator E :

E = On input x :

Step 1. Repeat for $i = 1, 2, 3, \dots$ (forever)

1a. Run M for i steps on the first i strings in Σ^* (sorted by length, then lex order) E.g., when $\Sigma = \{0, 1\}$, the order of strings is: $\varepsilon, 0, 1, 00, 01, 10, \dots$

1b. If M accepts a string w , print w

Enumerator (6)

- In the Proof of (2), we see that if a string is accepted by M , it will be printed by E eventually (why?), though it will be printed infinitely many times (why?)
- Recall that Turing-recognizable language is also called recursively enumerable language. The latter term actually originates from enumerator

Hilbert's 10th Problem

- In 1900, David Hilbert delivered a famous talk in International Congress of Mathematicians
- He identified 23 math problems which he thinks are important in the coming century
- The **10th Problem**: Given a multi-variable polynomial **F** with integral coefficients (such as $F(x,y,z) = 6x^3yz^2 + 3xy^2 - 27$).

Any **algorithm** can tell if we have an integral root for **F** = 0? [E.g., in this case, $x=y=1, z=2$ is an integral root for $F(x,y,z)=0$]

Hilbert's 10th Problem (2)

- However, what is meant by an **algorithm**?
- Roughly speaking, one meaning of algorithm is: **a set of steps** for solving a problem, such that when we are provided with **unlimited supply of pencils and papers**, we can **blindly** follow these steps and solve the problem
- There is no precise definition, until in 1936, two separate papers, one from Alonzo Church and one from Alan Turing, try to define it

Church-Turing Thesis

- Turing restricts that each algorithm step must be simple enough for a TM to perform
- Church's definition of algorithm is based on something called λ -calculus
- Surprisingly, these two definitions are shown to be equivalent!! (That is, a problem P can be solved by an algorithm with Turing's definition if and only if P can be solved by some algorithm with Church's definition)
 - Later (in 1970), Yuri Matijasevič proves that, under their definition, no algorithm can test whether a multi-variable polynomial has integral root

Church-Turing Thesis (2)

- Also, it seems that all known problems that are solvable by an "algorithm" (with our "intuitive" and "non-precise" definition) are exactly the problems solvable by TM
- Therefore, Steven Kleene (1943) makes the following **conjecture** in his paper, which is now known as the **Church-Turing Thesis**:
"If a problem is intuitively solvable, it can be solved by TM"

Solving Problem by TM (example)

- Let A be the language
 $\{ \langle G \rangle \mid G = \text{undirected connected graph} \}$
where $\langle G \rangle$ the encoding of G
- That is, given an undirected graph G , we want to determine if G is connected
- How to solve it by TM?

Solving Problem by TM (example)

M = "On input $\langle G \rangle$

Step 1. Select first node of G and mark it

Step 2. Repeat the following stage until no new nodes are marked:

2a. For each node in G , mark it if it is attached to a marked node

Step 3. Scan all nodes. If all are marked, **accept**. Otherwise, **reject**.

Next Time

- Decidable Language
 - Can be decided by some algorithm
- Undecidable Language
 - No algorithm can decide it