

# Stabbing Problem

# Outline

- Stabbing problem
- Method 1
- Method 2
- Related problems

# Stabbing Problem

- Given a set of  $n$  line segments  $S$
- Input: query point  $q$
- Output: the intervals that contain  $q$



# Stabbing Problem

- Brute force algorithm:
  - For query point  $q$  and every interval  $s_i$  in  $S$ , check if  $q$  overlaps with  $s_i$
  - Time complexity:  $O(n)$

# Stabbing Problem

- Brute force algorithm:
  - For query point  $q$  and every interval  $s_i$  in  $S$ , check if  $q$  overlaps with  $s_i$
  - Time complexity:  $O(n)$
- Can we do faster?

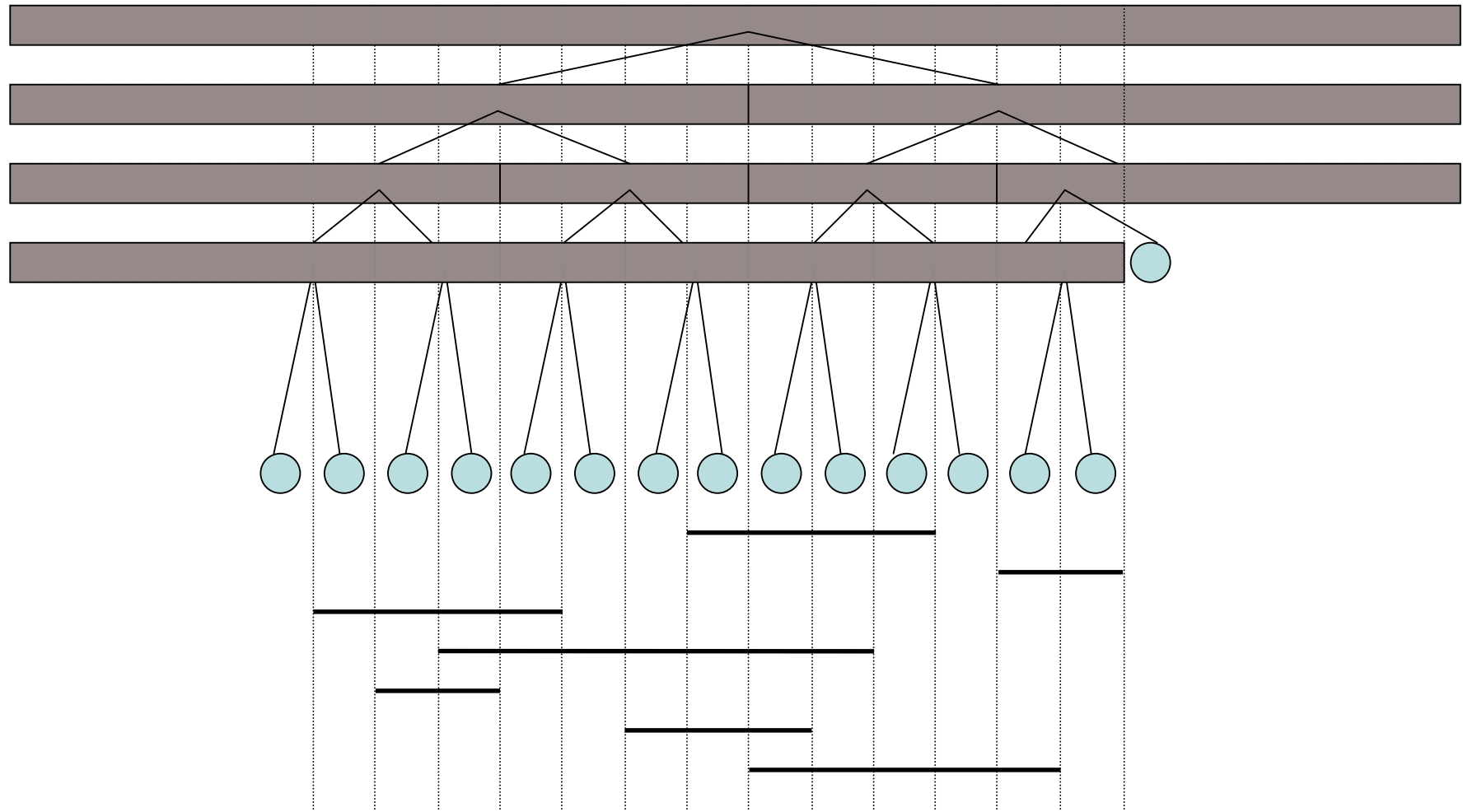
# Outline

- Stabbing problem
- Method 1 - segment tree

# Segment Tree

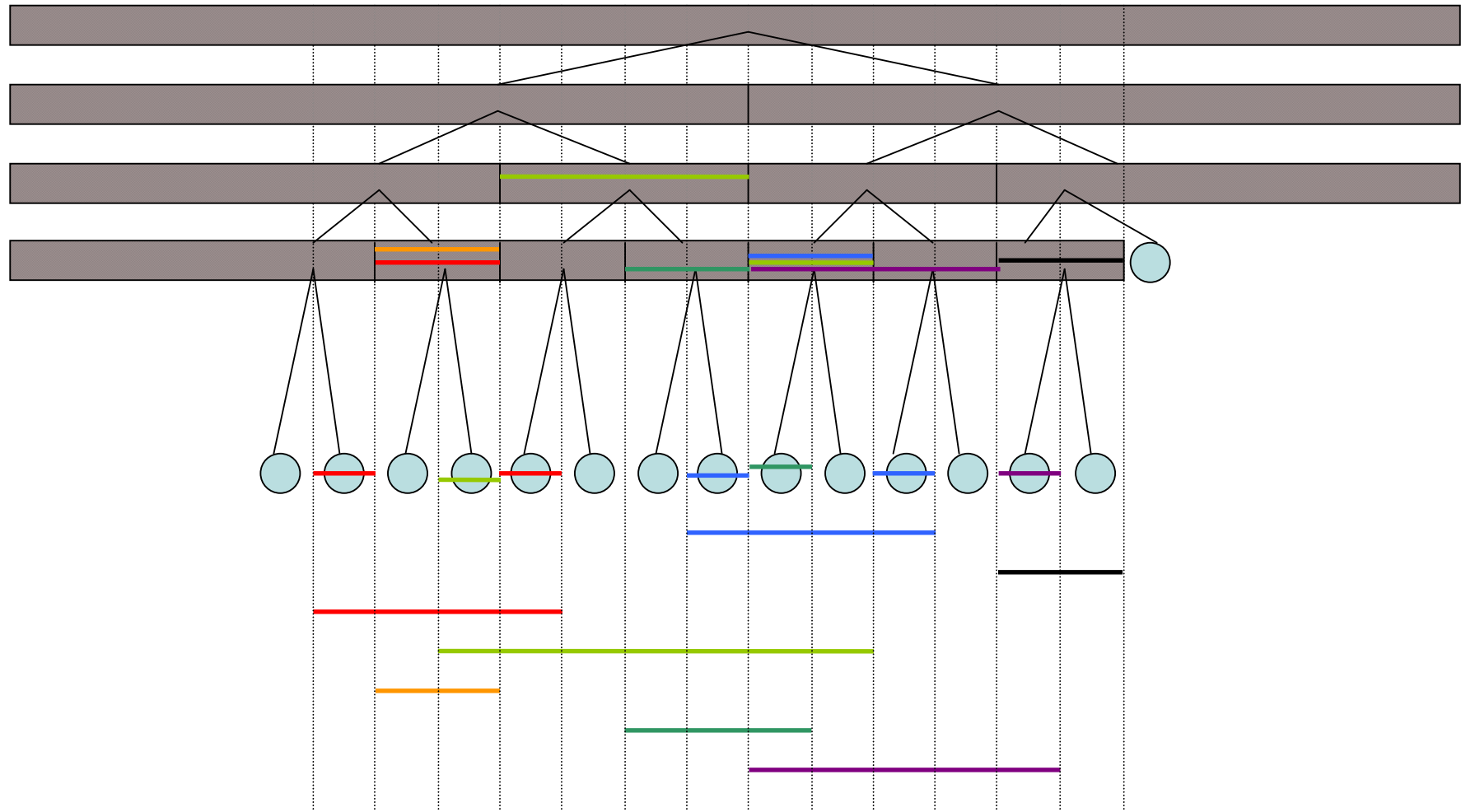
- Preprocess:
  - Step 1: Sort by all the start points and end points
  - Step 2: By the  $2n$  points, build a balanced binary search tree  $T$ 
    - Height of  $T = O(\log n)$
  - Step 3: Insert the line segments into  $T$ 
    - Insert a line segment needs  $O(\log n)$  time

# Example





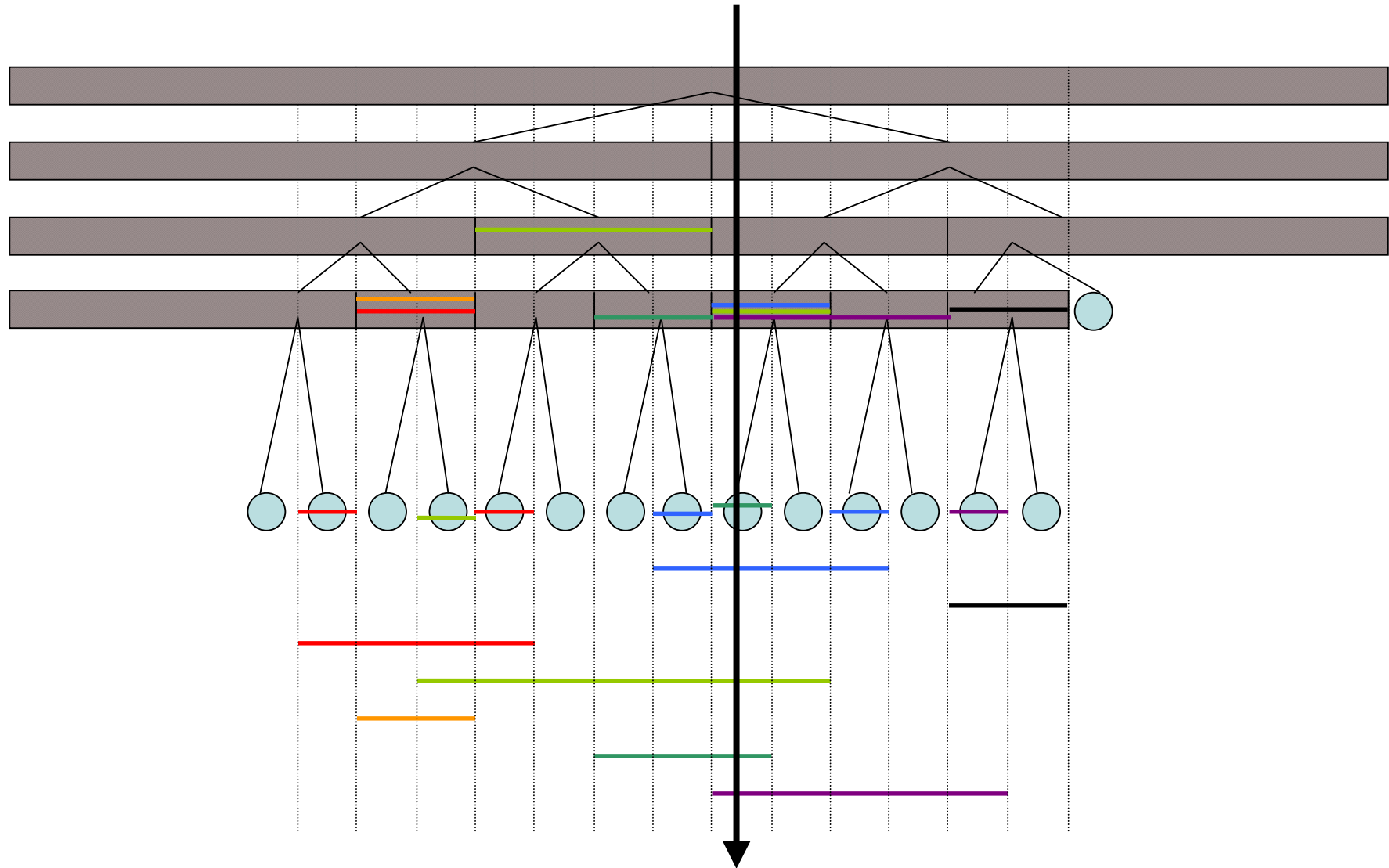
# Example



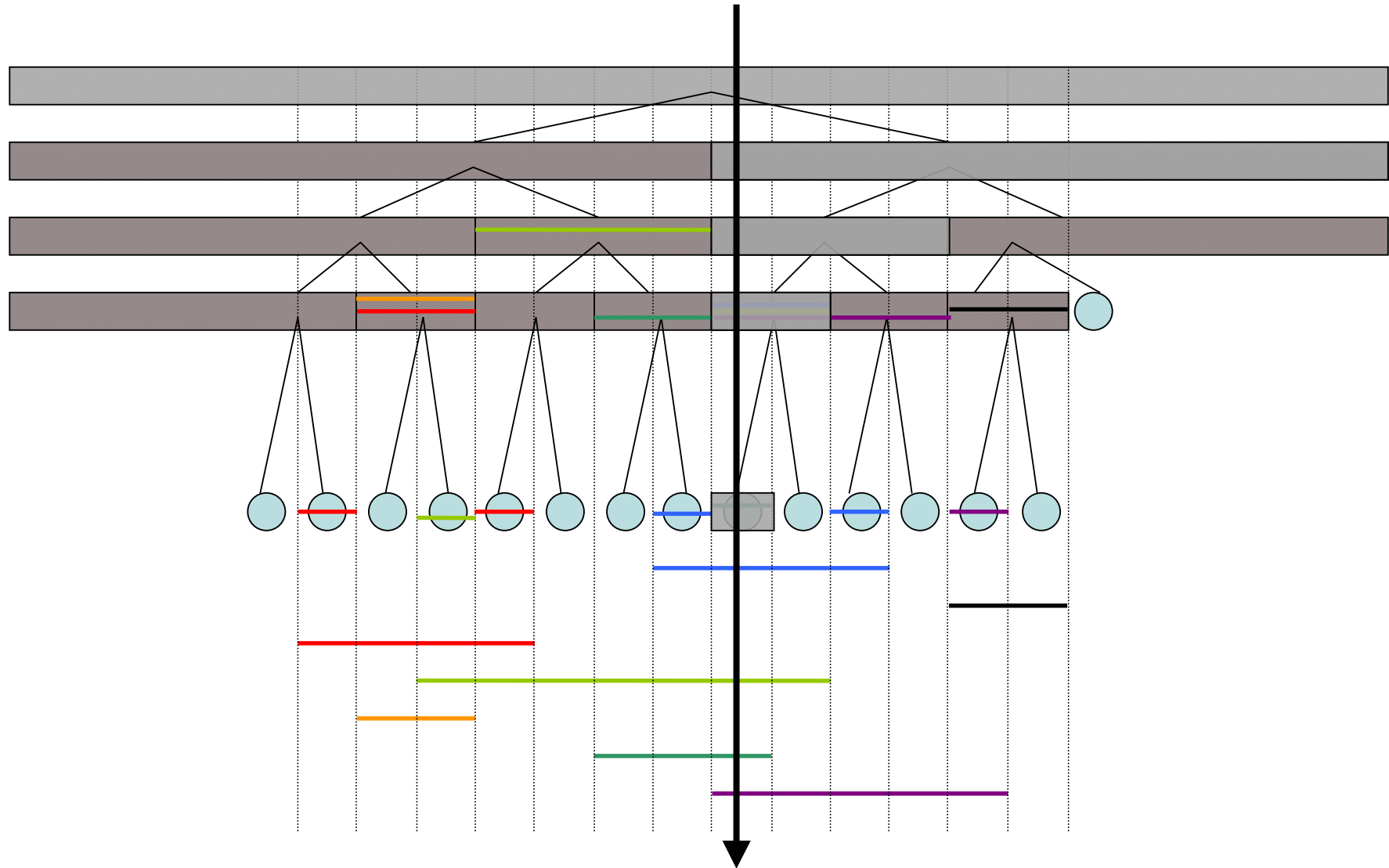
# Segment Tree

- Property: any segment is stored at most twice at each level of  $T$
- Space complexity:  $O(n \log n)$
- Preprocessing time:  $O(n \log n)$
  
- Note: every node represents a segment

# Segment Tree Query



# Segment Tree Query



# Segment Tree

- Query time:
  - $O(\log n + k_1 + k_2 + k_3 + \dots + k_{\log n})$   
=  $O(\log n + k)$
  - $k_L$ : number of nodes reported on level  $L$
- Output-sensitive
  - algorithms whose running time depends not only on the size of the input but also on the size of the output

# Outline

- Stabbing problem
- Method 1 - segment tree
- Method 2 - interval tree

# Interval Tree

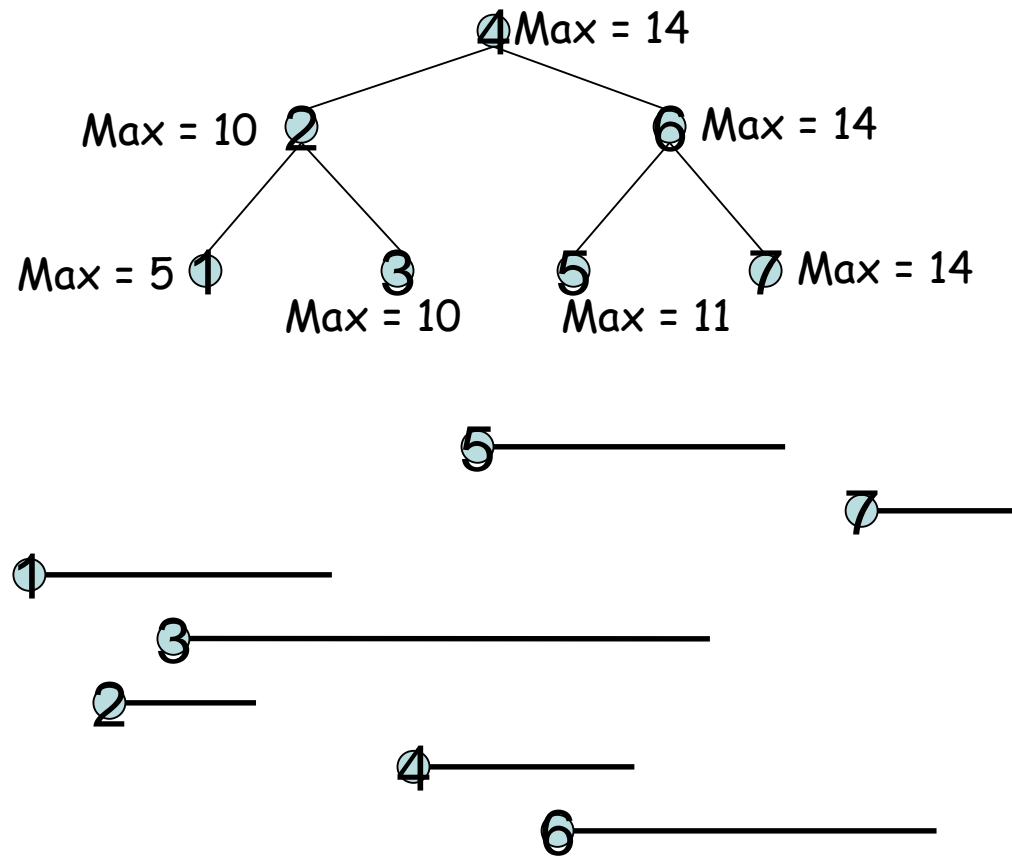
- Preprocess:
  - Build a balanced binary search tree  $T$  for the  $n$  line segments by the start points
    - Each node  $v$  of  $T$  has information of the line segment and  $Max$
    - $Max$ : position of the rightmost end points in subtree of root  $v$

# Interval Tree

- Preprocess time:
  - Build BBST:  $O(n \log n)$ 
    - Insert a line segment into T:  $O(\log n)$
  - Maintain Max:  $O(1)$



# Example



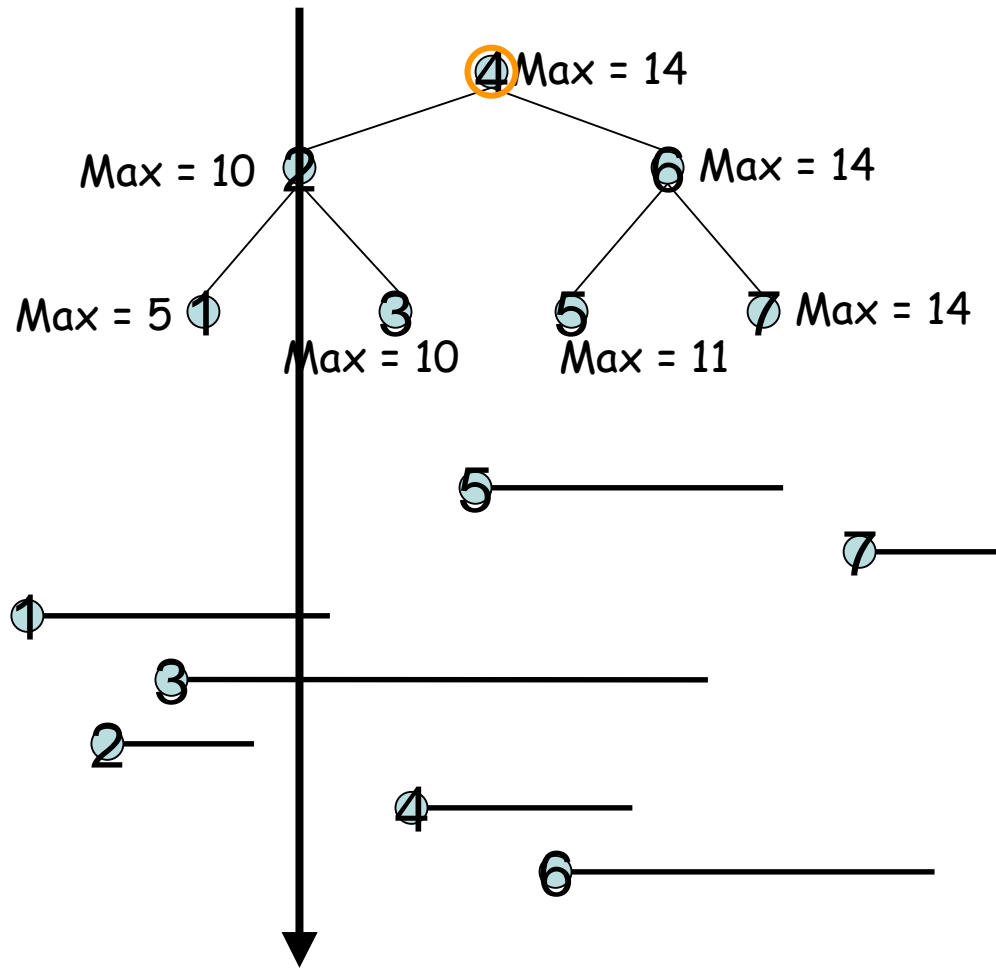
# Interval Tree

- Space:  $O(n)$ 
  - Each node represents a line segment
- Query time:  $O(k \log n)$

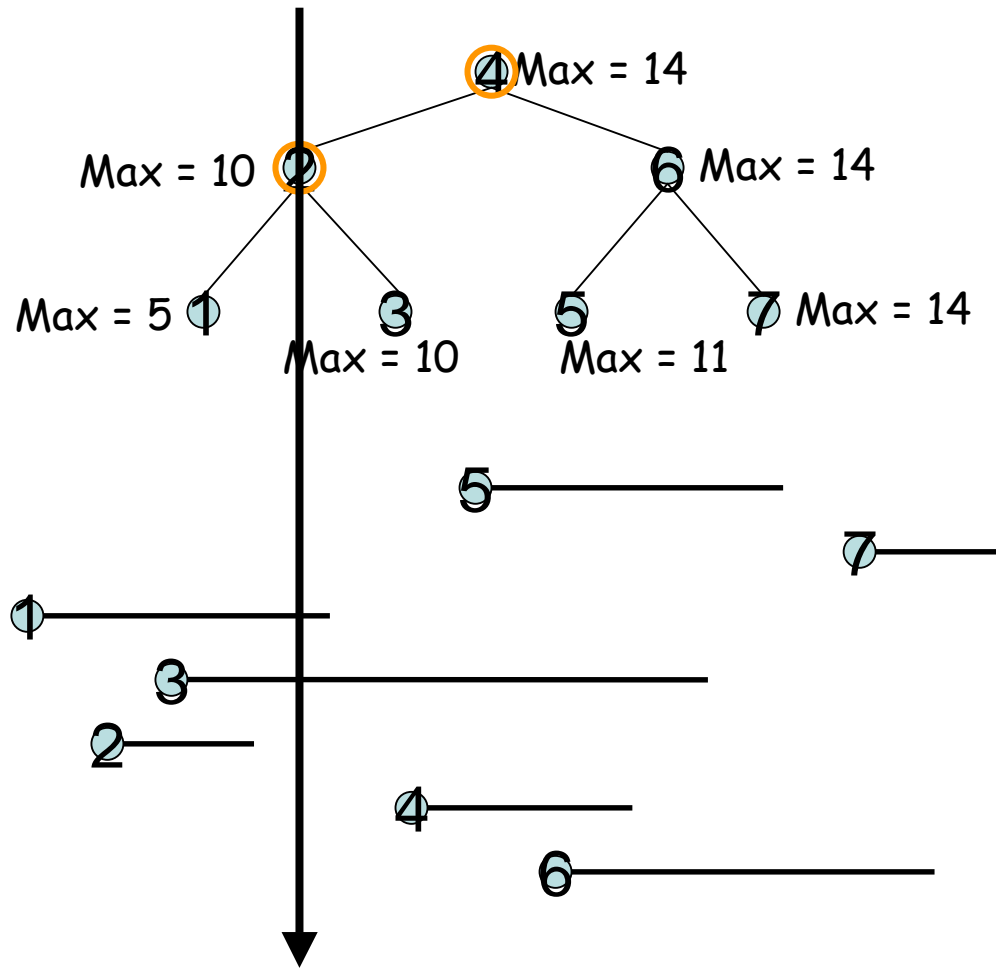
# Interval Tree

- Query:
  - Step 1: check if query point  $q$  intersects with the line segment in node  $x$ 
    - Yes  $\rightarrow$  report
  - Step 2: check if  $q > x.\text{max}$ 
    - Yes  $\rightarrow$  complete
  - Step 3: check if  $q > x.\text{startpoint}$ 
    - Yes  $\rightarrow$  recursively run on  $x.\text{leftchild}$  and  $x.\text{rightchild}$
    - No  $\rightarrow$  recursively run on  $x.\text{leftchild}$

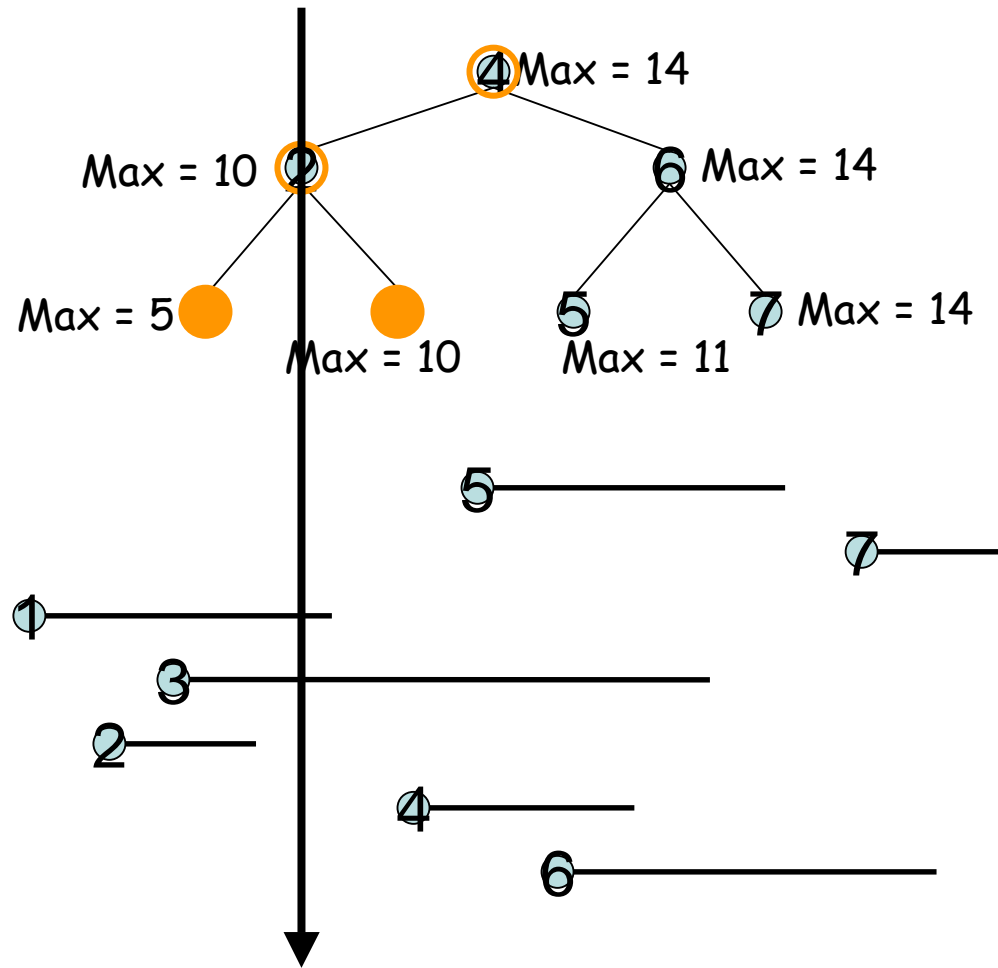
# Example



# Example



# Example



# Interval Tree

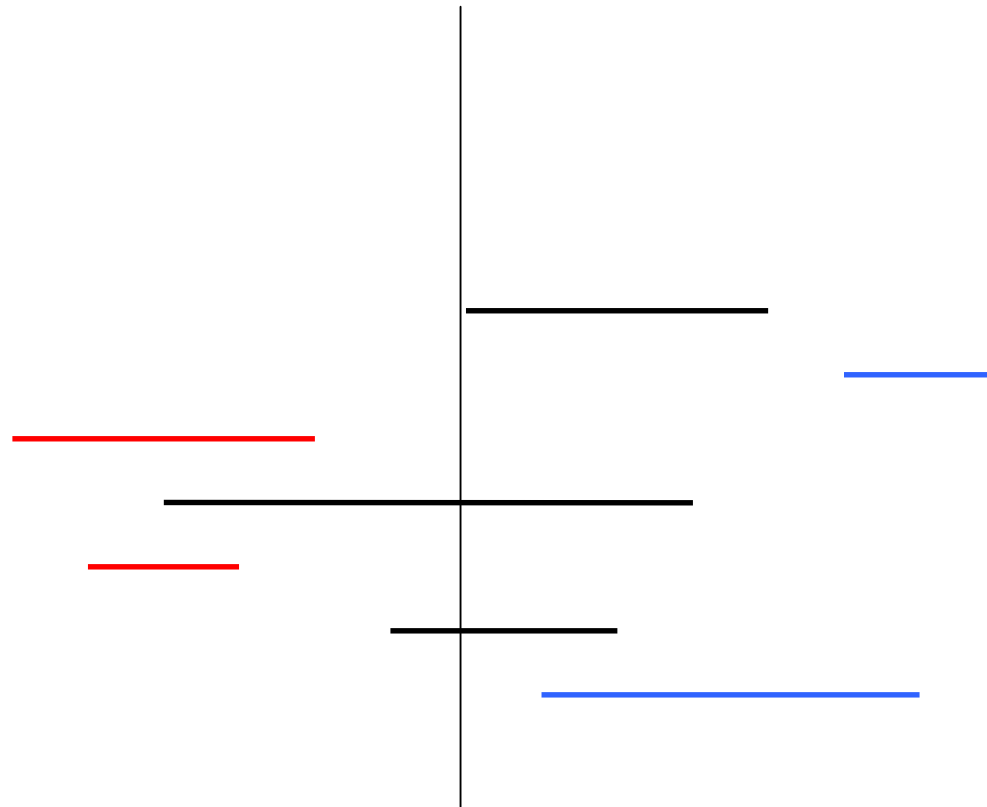
	$q < x.max$	$q > x.max$
$q < x.start$		
$q > x.start$		

# Outline

- Stabbing problem
- Method 1 - segment tree
- Method 2 - interval tree  
(a completely different version)



# Interval Tree 2



# Outline

- Stabbing problem
- Method 1 - segment tree
- Method 2 - interval tree
- **Related problems**

# Related Problem

- Higher-dimension Stabbing Problem
  - Solved by multi-level of segment trees
  - Space improvement if we use interval tree at deepest level
- Given a set of points, query rectangle
  - called Range Query Problem