

CS4311
Design and Analysis of
Algorithms

Lecture 11: Dynamic Programming III

Writing a Translation Program

- Suppose we want to design a program to translate English texts on food to Chinese
- First problem to solve:

Given an English word, can we quickly search for its Chinese equivalent?

E.g., Apple → 蘋果, Banana → 香蕉,
Pizza → 比薩, Burger → 漢堡,
Hotdog → 熱狗, Spaghetti → 意大利麵

Writing a Translation Program

- However, some English words may not have a Chinese equivalent
 - In this case, we report not found
- E.g., Biryani (a South Asian dish)
 - Burrito (a common Mexican food)
 - Jambalaya (a famous Louisiana dish)
 - Okonomiyaki (a kind of Japanese pizza)

Writing a Translation Program

- Let n = # of English words in our database with Chinese equivalent

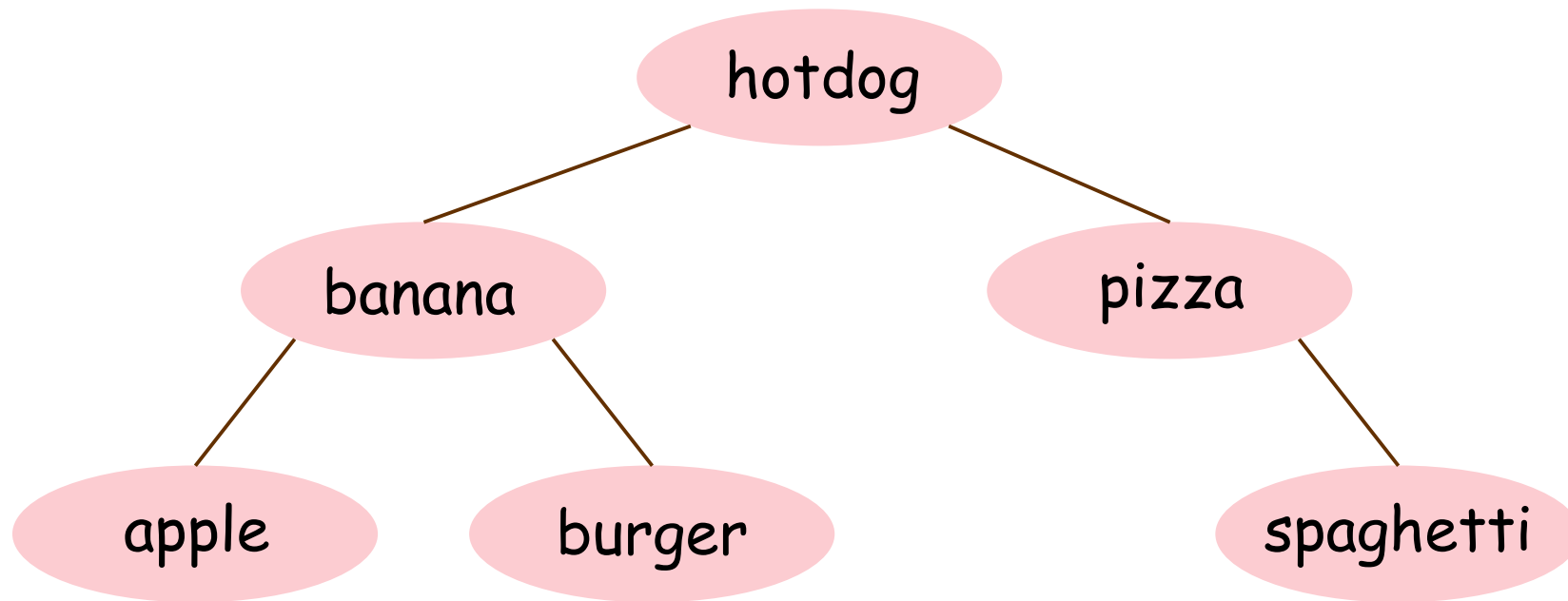
Solution 1: Hashing

- Good, but need a good hash function

Solution 2: Balanced Binary Search Tree

- worst-case $O(\log n)$ time per query

Balanced Binary Search Tree



Keys = words in the database

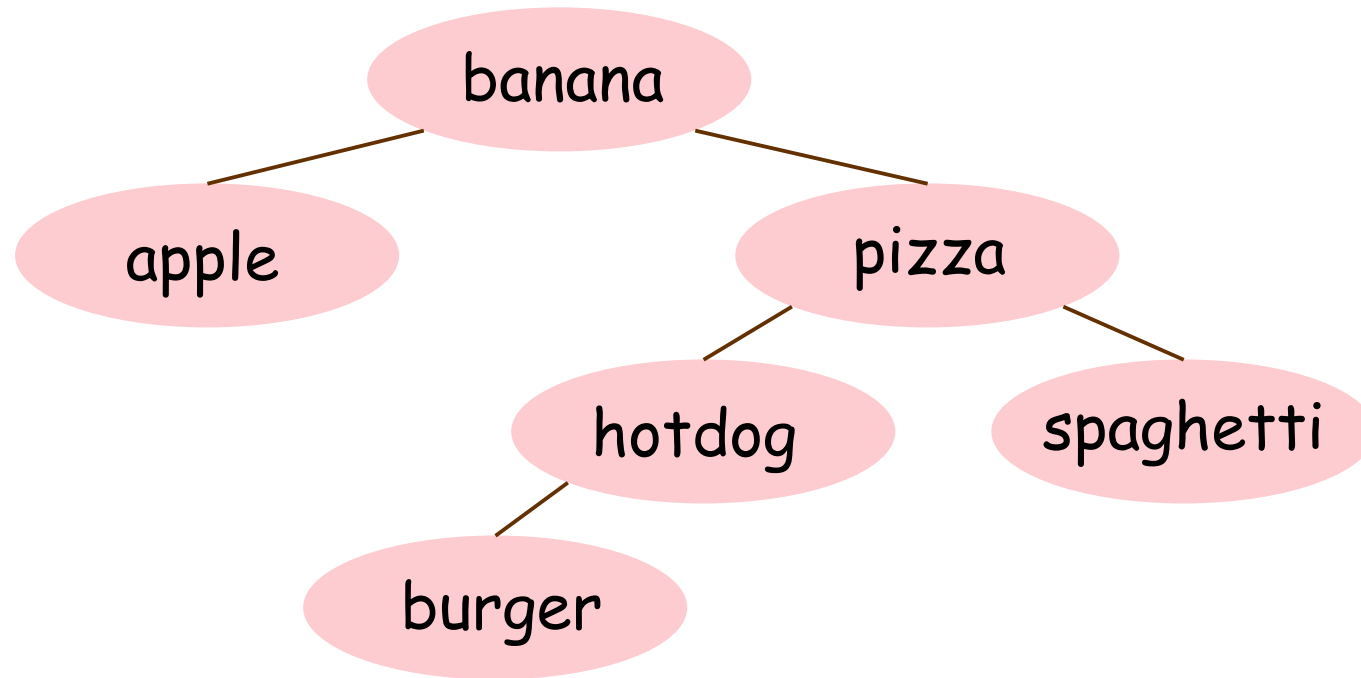
Writing a Translation Program

- In real life, different words may be searched with different frequencies
E.g., **apple** may be more often than **pizza**
- Also, there may be different frequencies for the **unsuccessful** searches
E.g., we may **unluckily** search for a word in the range **(hotdog, pizza)** more often than in the range **(spaghetti, $+\infty$)**

- Suppose your friend in Google gives you the probabilities of what a search will be:

< apple	0.01	= hotdog	0.02
= apple	0.21	(hotdog, pizza)	0.04
(apple, banana)	0.10	= pizza	0.04
= banana	0.18	(pizza, spaghetti)	0.11
(banana, burger)	0.05	= spaghetti	0.07
= burger	0.01	> spaghetti	0.04
(burger, hotdog)	0.12		

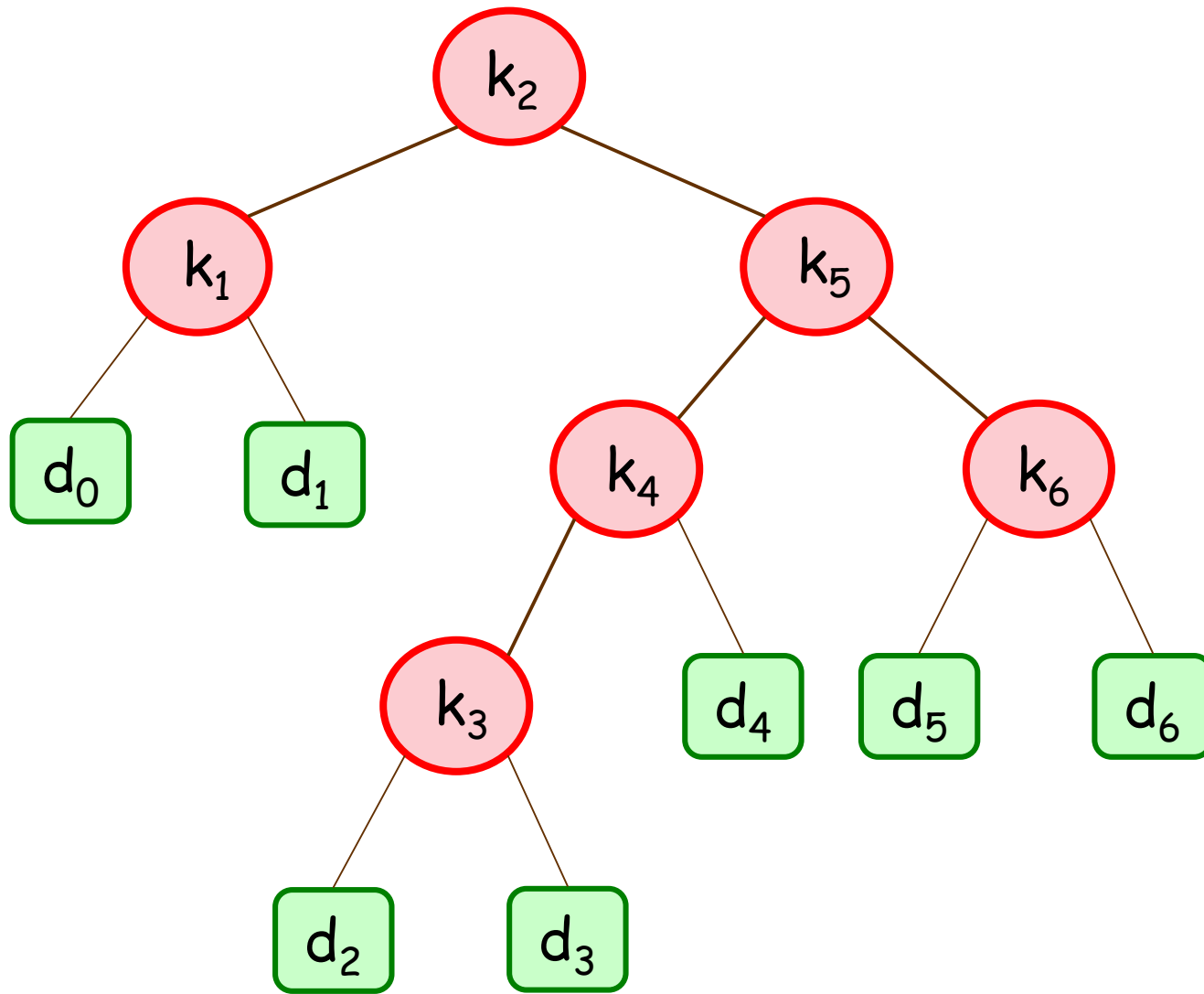
- Given these probabilities, we may want words that are searched **more frequently** to be **nearer** the root of the search tree



This tree has better **expected** performance

Expected Search Time

- To handle unsuccessful searches, we can modify the search tree slightly (by adding **dummy** leaves), and define the **expected search time** as follows:
- Let $k_1 < k_2 < \dots < k_n$ denote the n keys, which correspond to the **internal nodes**
- Let $d_0 < d_1 < d_2 < \dots < d_n$ be **dummy** keys for ranges of the unsuccessful search
→ dummy keys correspond to **leaves**



Search tree of Page 9 after modification

Search Time

Lemma: Based on the modified search tree:

- when we search for a word k_i ,
search time = node-depth(k_i)
- when we search for a word in range d_j ,
search time = node-depth(d_j)

Expected Search Time

- Let $p_i = \Pr(k_i \text{ is searched})$
- Let $q_j = \Pr(\text{word in } d_j \text{ is searched})$

So,
$$\sum_i p_i + \sum_j q_j = 1$$

Expected search time

$$= \sum_i p_i \text{node-depth}(k_i) + \sum_j q_j \text{node-depth}(d_j)$$

Optimal Binary Search Tree

Question:

Given the probabilities p_i and q_j ,
can we construct a binary search tree
whose expected search time is minimized?

Such a search tree is called an
Optimal Binary Search Tree

Optimal Substructure

Let T = optimal BST for the keys
($k_i, k_{i+1}, \dots, k_j; d_{i-1}, d_i, \dots, d_j$).

Let L and R be its left and right subtrees.

Lemma: Suppose k_r is the root of T . Then,

- L must be an optimal BST for the keys
($k_i, k_{i+1}, \dots, k_{r-1}; d_{i-1}, d_i, \dots, d_{r-1}$)
- R must be an optimal BST for the keys
($k_{r+1}, k_{r+2}, \dots, k_j; d_r, d_{r+1}, \dots, d_j$)

Optimal Substructure

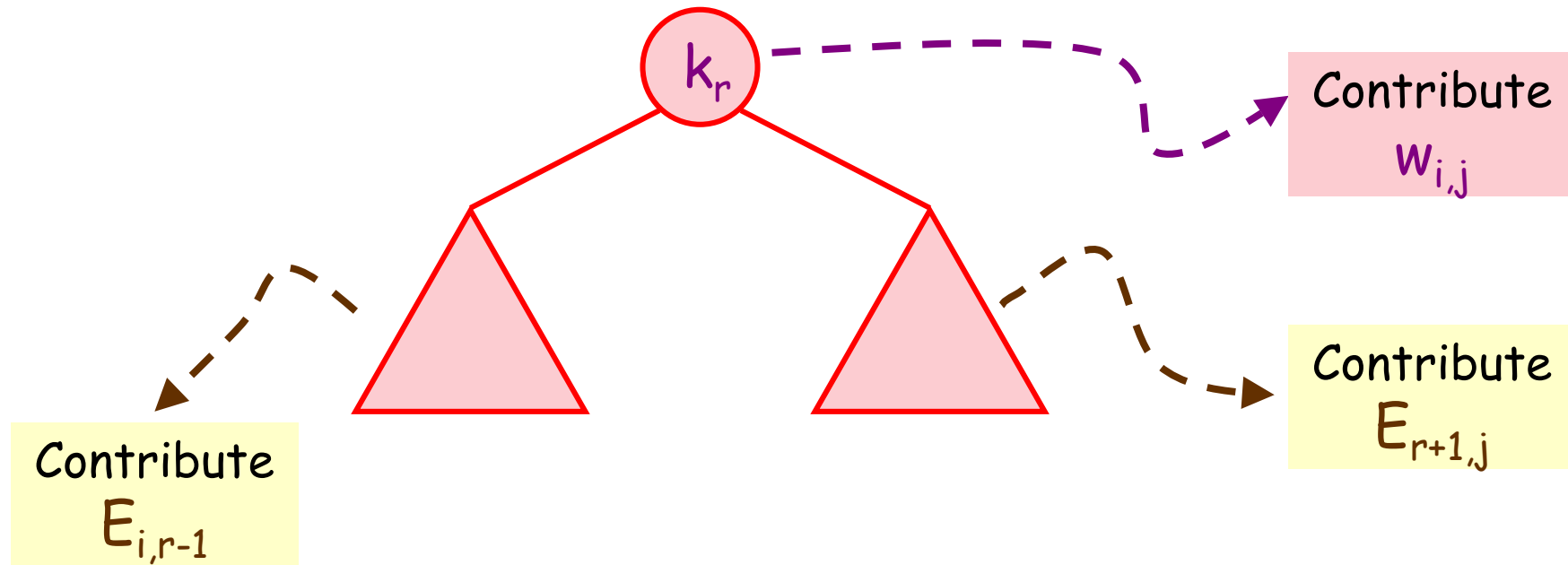
Let $E_{i,j}$ = expected time spent with the keys
(k_i, k_{i+1}, \dots, k_j ; d_{i-1}, d_i, \dots, d_j) in
optimal BST

Let $w_{i,j}$ = $\sum_{s=i \text{ to } j} p_s + \sum_{t=i-1 \text{ to } j} q_t$
= sum of the probabilities of keys
(k_i, k_{i+1}, \dots, k_j ; d_{i-1}, d_i, \dots, d_j)

Optimal Substructure

Lemma: For any $j \geq i$,

$$E_{i,j} = \min_r \{ E_{i,r-1} + E_{r+1,j} + W_{i,j} \}$$



Optimal Binary Search Tree

Define a function `Compute_E(i,j)` as follows:


```
Compute_E(i, j) /* Finding  $e_{i,j}$  */  
1. if (i == j+1) return  $q_j$ ; /* Exp time with key  $d_j$  */  
2. min =  $\infty$ ;  
3. for (r = i, i+1, ..., j) {  
    g = Compute_E(i, r-1) + Compute_E(r+1, j) +  $w_{i,j}$  ;  
    if (g < min) min = g;  
}  
4. return min ;
```

Optimal Binary Search Tree

Question: We want to get $\text{Compute_E}(1,n)$
What is its running time?

- Similar to Matrix-Chain Multiplication, the recursive function runs in $\Omega(3^n)$ time
- In fact, it will examine at most once for all possible binary search tree \rightarrow Running time = $O(C(2n-2, n-1)/n)$

Catalan Number



Overlapping Subproblems

Here, we can see that :

To Compute $E(i,j)$ and $E(i,j+1)$,
there are many **COMMON** subproblems:
 $E(i,i+1), \dots, E(i,j-1)$

So, in our recursive algorithm, there are
many **redundant** computations !

Question: Can we avoid it ?

Bottom-Up Approach

- Let us create a 2D table E to store all $E_{i,j}$ values once they are computed
- Let us also create a 2D table W to store all $w_{i,j}$

We first compute all entries in W .

Next, we compute $E_{i,j}$ for $j-i = 0, 1, 2, \dots, n-1$

Bottom-Up Approach

`BottomUp_E()` /* Finding min #operations */

1. Fill all entries of W

2. for $j = 1, 2, \dots, n$, set $E[j+1, j] = q_j$;

3. for (length = 0, 1, 2, ..., n-1)

 Compute $E[i, i+length]$ for all i ;

 // From W and $E[x, y]$ with $|x-y| < length$

4. return $E[1, n]$;

Running Time = $\Theta(n^3)$

Remarks

- Again, a slight change in the algorithm allows us to get the exact structure of the optimal binary search tree
- Also, we can make minor changes to the recursive algorithm and obtain a memoized version (whose running time is $O(n^3)$)