CS4311 Design and Analysis of Algorithms

Lecture 10: Dynamic Programming II

- Let A be a matrix of dimension $p \times q$ and B be a matrix of dimension $q \times r$
- Then, if we multiply matrices A and B, we obtain a resulting matrix C = AB whose dimension is $p \times r$
- We can obtain each entry in C using q operations → in total, pqr operations

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Example:

$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,1} & a_{2,2} & a_{2,3} \end{pmatrix} \begin{pmatrix} b_{1,1} & b_{1,2} \\ b_{2,1} & b_{2,2} \\ b_{3,1} & b_{3,2} \end{pmatrix} = \begin{pmatrix} c_{1,1} & c_{1,2} \\ c_{2,1} & c_{2,2} \end{pmatrix}$$

How to obtain $c_{1,2}$?

- In fact, $((A_1A_2)A_3) = (A_1(A_2A_3))$ so that matrix multiplication is associative
- → Any way to write down the parentheses gives the same result

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E.g., (((A_1A_2)A_3)A_4) = ((A_1A_2)(A_3A_4))
= (A_1((A_2A_3)A_4)) = ((A_1(A_2A_3))A_4)
= (A_1(A_2(A_3A_4)))
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Question: Why do we bother this?

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Because different computation sequence may use different number of operations! E.g., Let the dimensions of A_1, A_2, A_3 be: 1\times100, 100\times1, 1\times100, respectively #operations to get ((A_1A_2)A_3) = ?? #operations to get (A_1(A_2A_3)) = ??
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Optimal Substructure

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Lemma: Suppose that to multiply B_1, B_2, ..., B_j,
  the way with minimum #operations is to:
   (i) first, obtain B<sub>1</sub>B<sub>2</sub> ... B<sub>x</sub>
   (ii) then, obtain B_{x+1} \dots B_i
   (iii) finally, multiply the matrices of
         part (i) and part (ii)
Then, the matrices in part (i) and part (ii)
  must be obtained with min #operations
```

Optimal Substructure

Let $f_{i,j}$ denote the min #operations to obtain the product $A_i A_{i+1} \dots A_j$

$$\rightarrow$$
 $f_{i,i} = 0$

Let r_k and c_k denote #rows and #cols of A_k Then, we have:

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Lemma: For any j > i,

f_{i,j} = \min_{x} \{ f_{i,x} + f_{x+1,j} + r_i c_x c_j \}
```

Matrix-Chain Multiplication

Define a function Compute_F(i,j) as follows: Compute_F(i, j) /* Finding f_{i,i} */ 1. if (i == j) return 0; 2. $m = \infty$: 3. for (x = i, i+1, ..., j-1) { $g = Compute_F(i,x) + Compute_F(x+1,j) + r_i c_x c_j$; if (q < m) m = q; 4. return m:

Matrix-Chain Multiplication

Question: Time to get Compute_F(1,n)?

• By substituion method, we can show that Running time = $\Omega(3^n)$

Remark: On the other hand, #operations for each possible way of writing parentheses are computed at most once → Running time = O(C(2n-2,n-1)/n)

Catalan Number

Overlapping Subproblems

Here, we can see that:

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To Compute_F(i,j) and Compute_F(i,j+1), both have many COMMON subproblems: Compute_F(i,i+1), ..., Compute_F(i,j-1)
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So, in our recursive algorithm, there are many redundant computations!

Question: Can we avoid it?

Bottom-Up Approach

• We notice that $f_{i,j} \text{ depends only on } f_{x,y} \text{ with } |x-y| < |i-j|$

- Let us create a 2D table F to store all f_{i,j} values once they are computed
- Then, compute $f_{i,j}$ for j-i=1,2,...,n-1

Bottom-Up Approach

```
BottomUp_F() /* Finding min #operations */
 1. for j = 1, 2, ..., n, set F[j, j] = 0;
 2. for (length = 1,2,..., n-1) {
       Compute F[i,i+length] for all i;
       // Based on F[x,y] with |x-y| < length
 3. return F[1,n];
```

Running Time = $\Theta(n^3)$

Remarks

- Again, a slight change in the algorithm allows us to get the exact sequence of steps (or the parentheses) that achieves the minimum number of operations
- Also, we can make minor changes to the recursive algorithm and obtain a memoized version (whose running time is O(n³))