

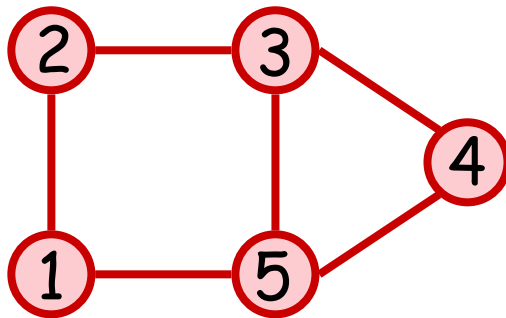
CS4311  
Design and Analysis of  
Algorithms

Lecture 22:  
Elementary Graph Algorithms I

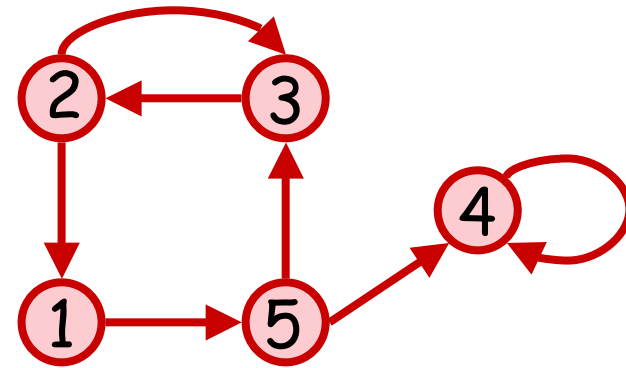
# About this lecture

- Representation of Graph
  - Adjacency List, Adjacency Matrix
- Breadth First Search

# Graph



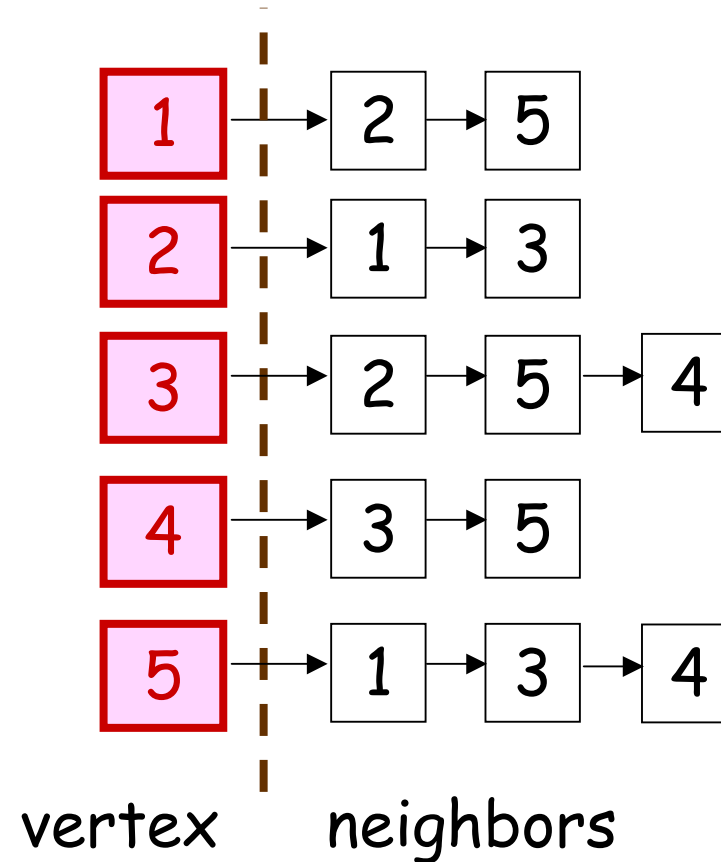
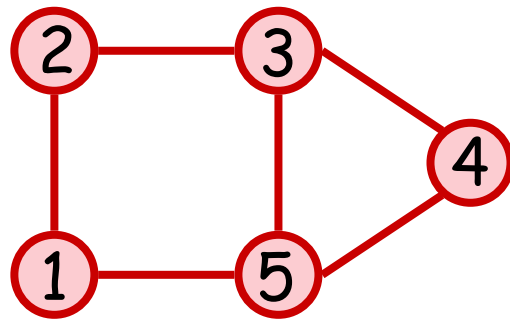
undirected



directed

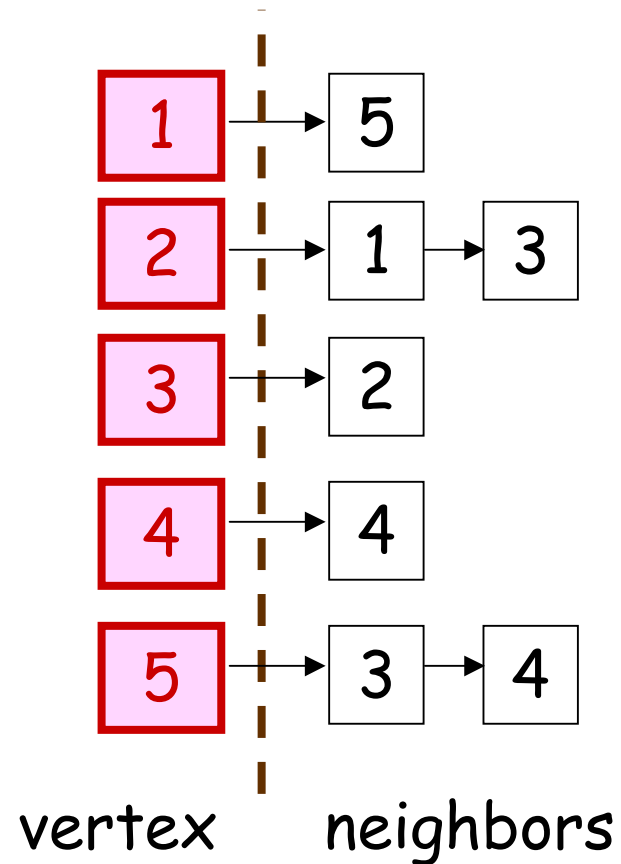
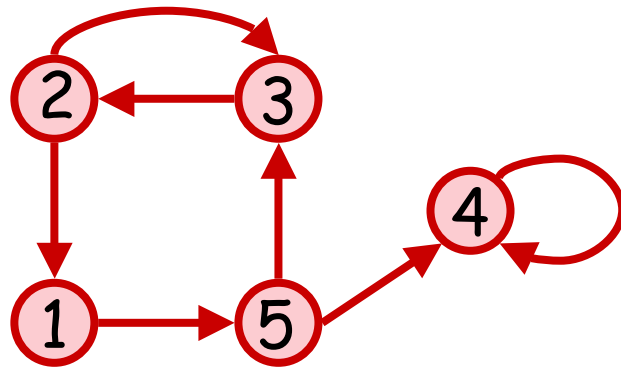
# Adjacency List (1)

- For each vertex  $u$ , store its neighbors in a linked list



# Adjacency List (2)

- For each vertex  $u$ , store its neighbors in a linked list

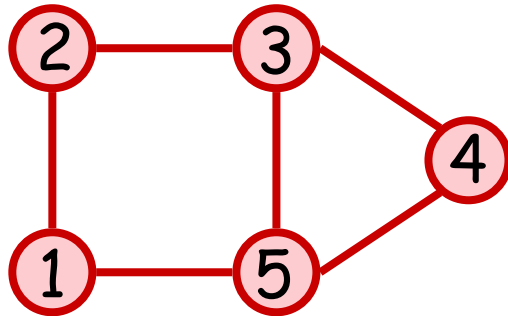


# Adjacency List (3)

- Let  $G = (V, E)$  be an input graph
- Using Adjacency List representation :
  - Space :  $O(|V| + |E|)$ 
    - Excellent when  $|E|$  is small
  - Easy to list all neighbors of a vertex
  - Takes  $O(|V|)$  time to check if a vertex  $u$  is a neighbor of a vertex  $v$
- can also represent **weighted** graph

# Adjacency Matrix (1)

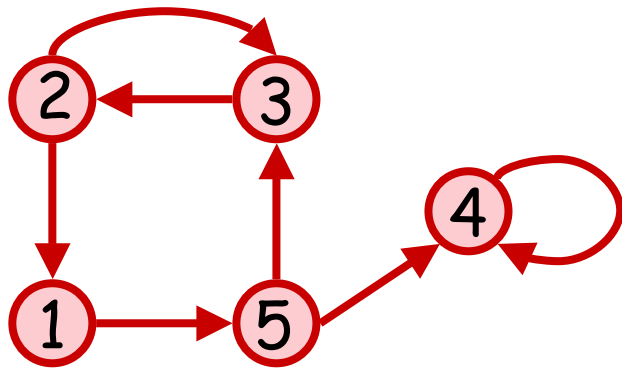
- Use a  $|V| \times |V|$  matrix  $A$  such that
$$A(u,v) = 1 \quad \text{if } (u,v) \text{ is an edge}$$
$$A(u,v) = 0 \quad \text{otherwise}$$



	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	0	0
3	0	1	0	1	1
4	0	0	1	0	1
5	1	0	1	1	0

# Adjacency Matrix (2)

- Use a  $|V| \times |V|$  matrix  $A$  such that
$$A(u,v) = 1 \quad \text{if } (u,v) \text{ is an edge}$$
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	1	2	3	4	5
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3	0	1	0	0	0
4	0	0	0	1	0
5	0	0	1	1	0



# Adjacency Matrix (3)

- Let  $G = (V, E)$  be an input graph
- Using Adjacency Matrix representation :
  - Space :  $O(|V|^2)$ 
    - Bad when  $|E|$  is small
  - $O(1)$  time to check if a vertex  $u$  is a neighbor of a vertex  $v$
  - $\Theta(|V|)$  time to list all neighbors
- can also represent **weighted** graph

# Transpose of a Matrix

- Let  $A$  be an  $n \times m$  matrix

Definition:

The transpose of  $A$ , denoted by  $A^T$ , is an  $m \times n$  matrix such that

$$A^T(u,v) = A(v,u) \quad \text{for every } u, v$$

→ If  $A$  is an adjacency matrix of an undirected graph, then  $A = A^T$

# Breadth First Search (BFS)

- A simple algorithm to find all vertices reachable from a particular vertex  $s$ 
  - $s$  is called source vertex
- Idea: Explore vertices in rounds
  - At Round  $k$ , visit all vertices whose shortest distance (#edges) from  $s$  is  $k-1$
  - Also, discover all vertices whose shortest distance from  $s$  is  $k$

# The BFS Algorithm

1. Mark  $s$  as discovered in Round 0

2. For Round  $k = 1, 2, 3, \dots,$

For (each  $u$  discovered in Round  $k-1$ )

{ Mark  $u$  as visited ;

Visit each neighbor  $v$  of  $u$  ;

If ( $v$  not visited and not discovered)

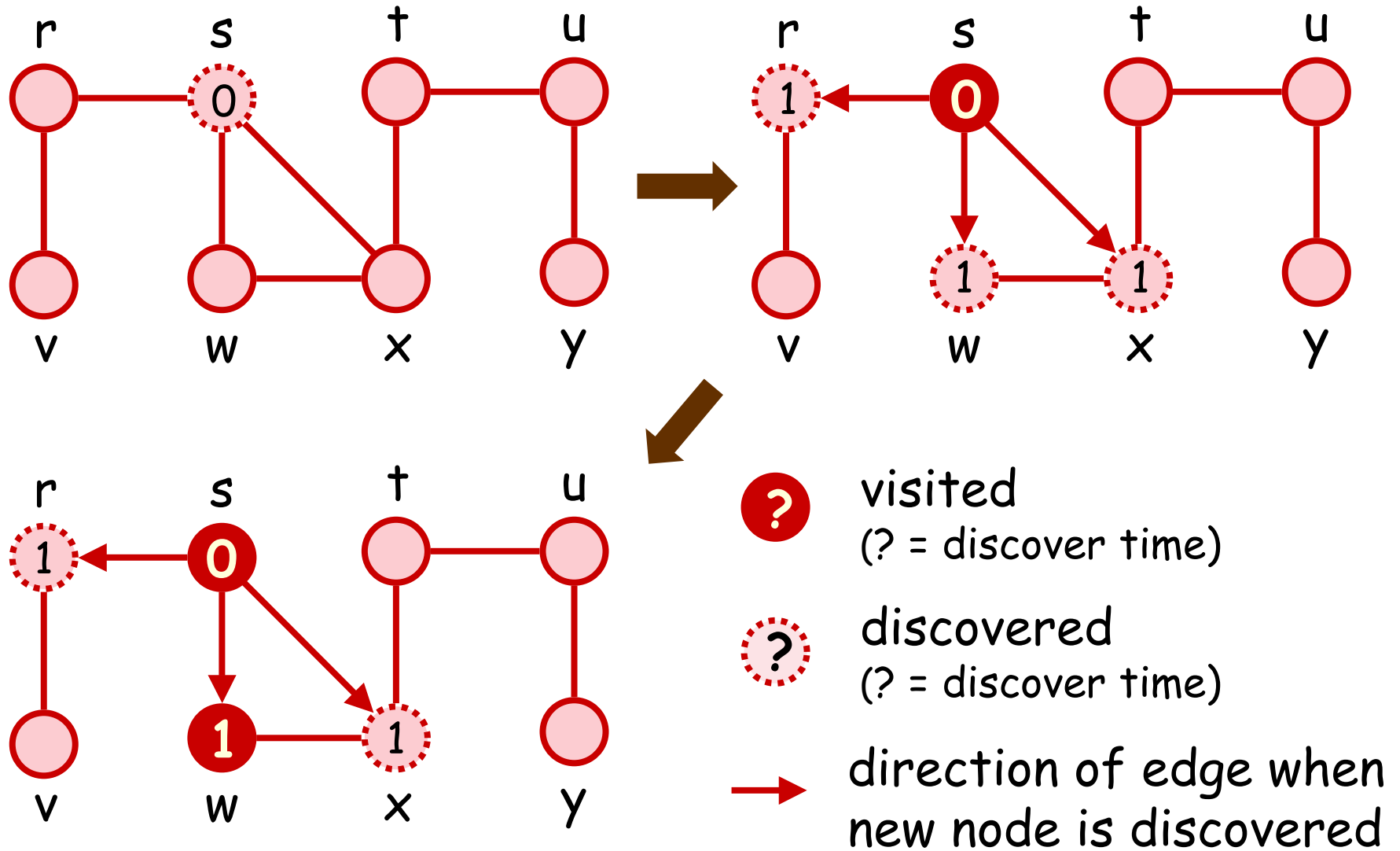
Mark  $v$  as discovered in Round  $k$  ;

}

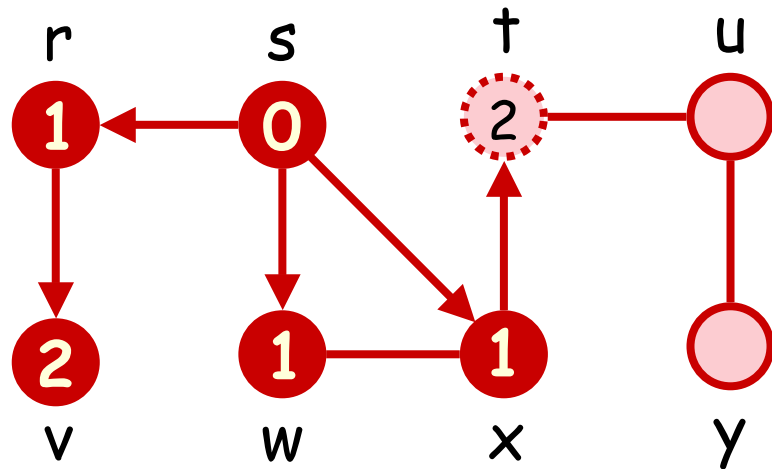
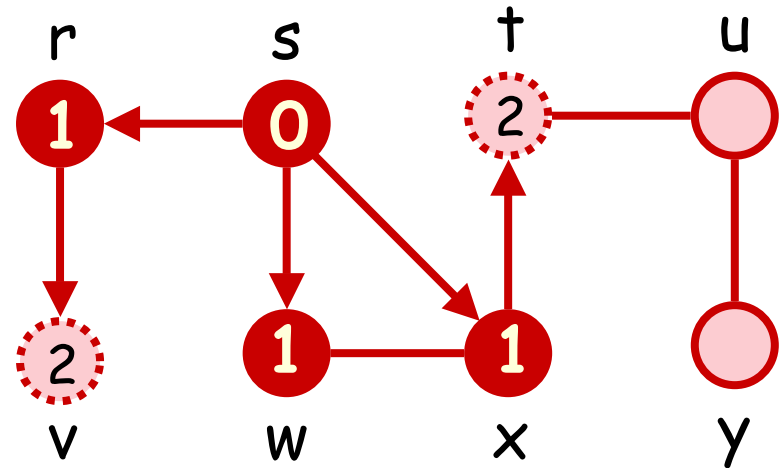
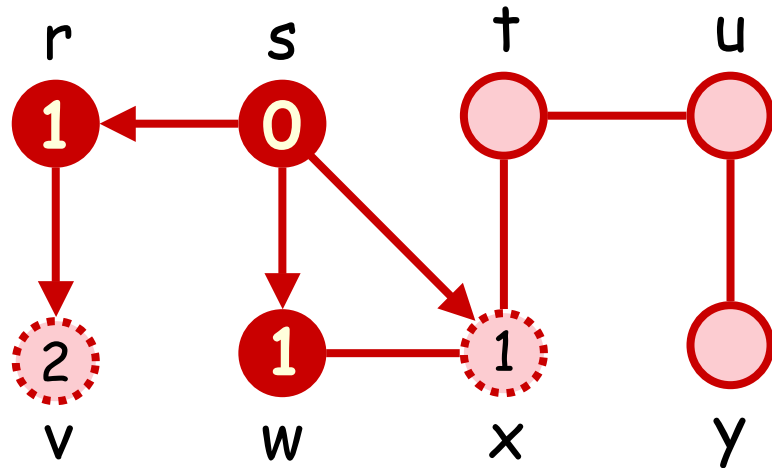


Stop if no vertices were discovered in Round  $k-1$

# Example ( $s = \text{source}$ )



# Example (s = source)



visited  
(? = discover time)

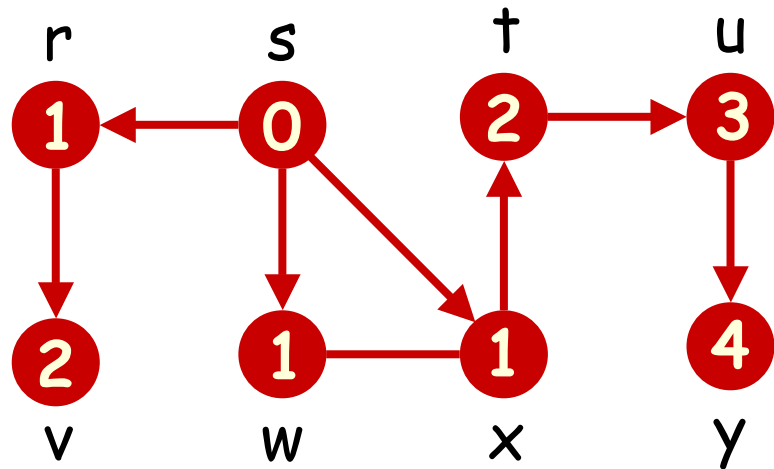
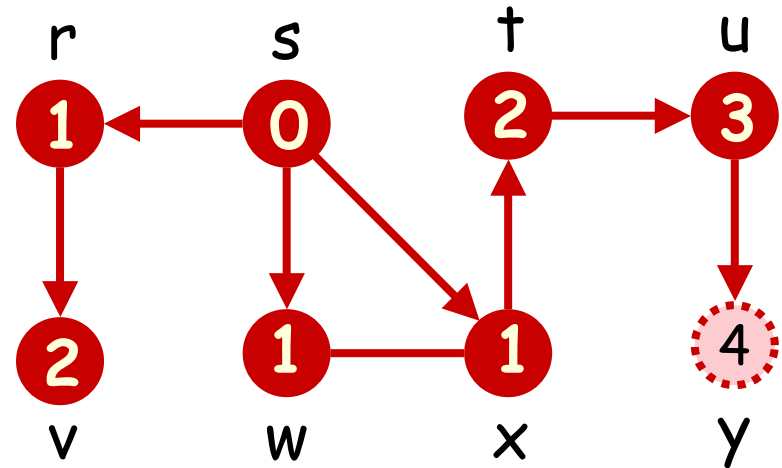
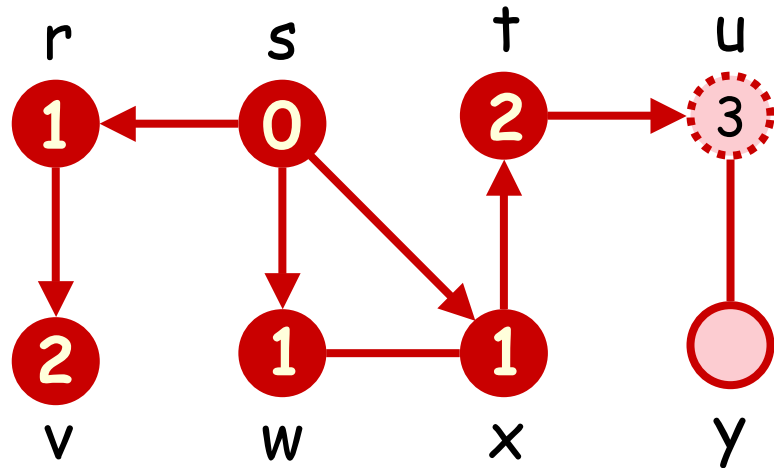


discovered  
(? = discover time)



direction of edge when  
new node is discovered

# Example (s = source)



visited  
(? = discover time)

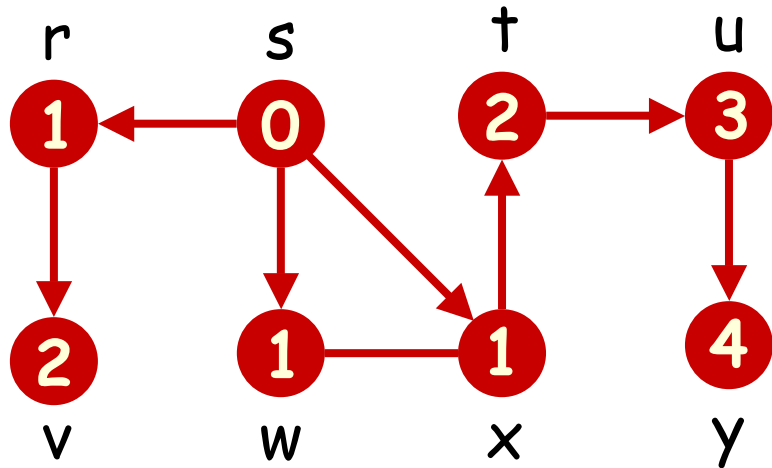


discovered  
(? = discover time)

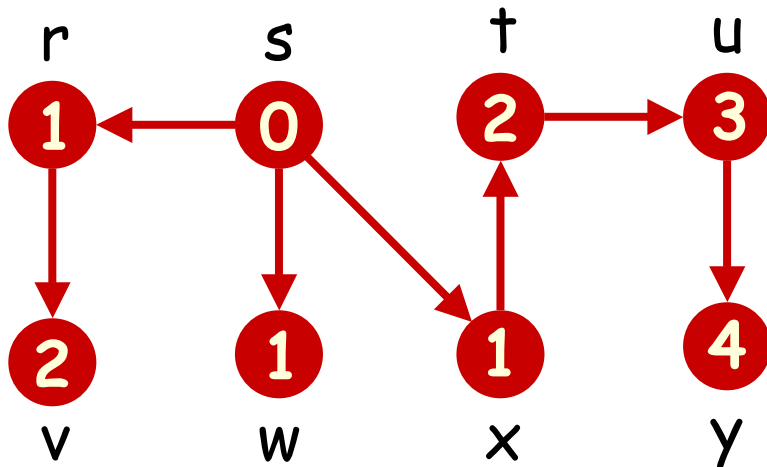


direction of edge when  
new node is discovered

# Example ( $s = \text{source}$ )



Done when no new node is discovered



The directed edges form a tree that contains all nodes **reachable** from  $s$

Called **BFS tree** of  $s$



# Correctness

- The correctness of BFS follows from the following theorem :

Theorem: A vertex  $v$  is discovered in Round  $k$  if and only if shortest distance of  $v$  from source  $s$  is  $k$

Proof: By induction

# Performance

- BFS algorithm is easily done if we use
  - an  $O(|V|)$ -size array to store discovered/visited information
  - a separate list for each round to store the vertices discovered in that round
- Since no vertex is discovered twice, and each edge is visited at most twice (why?)
  - Total time:  $O(|V|+|E|)$
  - Total space:  $O(|V|+|E|)$

# Performance (2)

- Instead of using a separate list for each round, we can use a common queue
  - When a vertex is **discovered**, we put it at the end of the queue
  - To pick a vertex to **visit** in Step 2, we pick the one at the front of the queue
  - Done when no vertex is in the queue
- ➔ No improvement in time/space ...
- ➔ But algorithm is simplified

**Question:** Can you prove the correctness of using queue?