




CS4311

Design and Analysis of Algorithms

Lecture 21: Data Structures for Disjoint Sets II

About this lecture

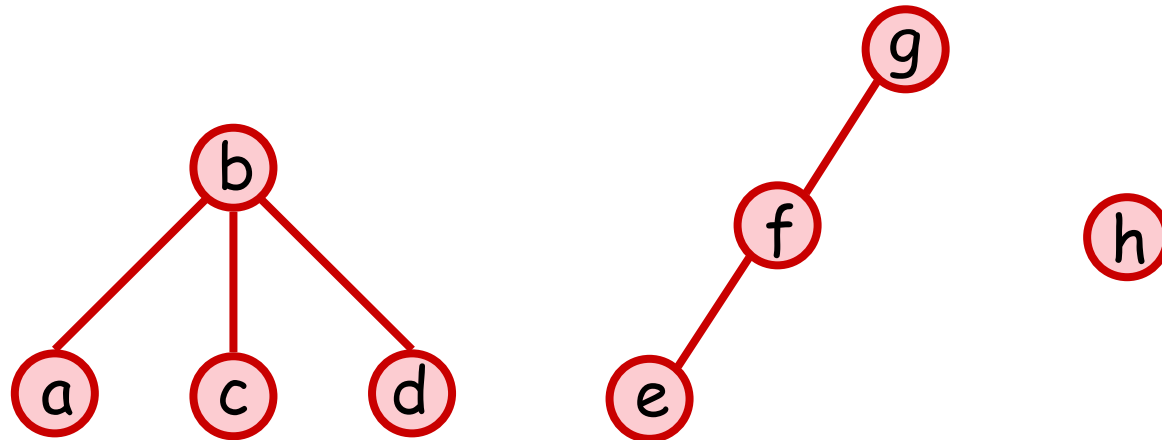
- Data Structure for Disjoint Sets
 - Support **Union** and **Find** operations
- Various Methods:
 1. Linked List
 2. Union by Size  (this lecture)
 3. Union by Rank 
 4. **Union by Rank + Path Compression** 

Disjoint-Set Forest

- Another popular method to maintain disjoint sets is by a **forest**
 - Each set \Leftrightarrow a **separate** rooted tree
 - Representative \Leftrightarrow **root** of tree
- Unlike the linked lists implementation, each element now points only to its **parent** (and does not directly point to the representative)

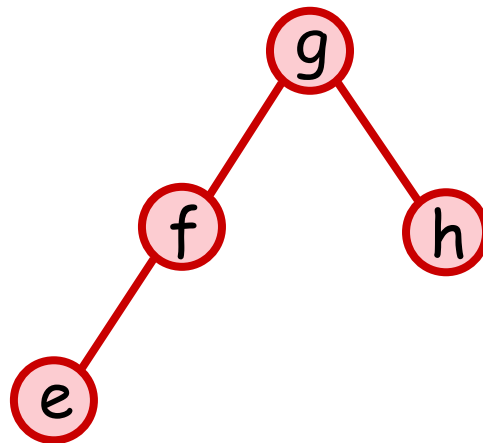
Example

Current dynamic sets : $\{ \{a,b,c,d\}, \{e,f,g\}, \{h\} \}$



Disjoint-Set Forest

- To perform $\text{Union}(x,y)$, we join the trees containing x and containing y , by **linking** their roots
- E.g. $\text{Union}(f,h)$ in previous example gives:



Disjoint-Set Forest

- Let H_{\max} = max height of all trees
- In the worst-case:

Make-Set : $\Theta(1)$ time

Find or Union : $O(H_{\max})$ time

→ m operations on n elements :

worst-case $\Theta(mn)$ time

Union By Size

- Let us apply a union-by-size heuristic :

To perform Union, we link root of the smaller tree to root of the larger tree

- $H_{\max} = O(\log n)$ (how to prove??)
- m operations : $\Theta(m \log n)$ time

Union By Rank

- A similar heuristic is called union-by-rank
- Each node keeps track of its **rank** - an **upper bound** on the height of the node
 - In a single-node tree (created by *Make-Set*)
rank of root = 0

To perform **Union**, we link root with smaller rank to root with larger rank

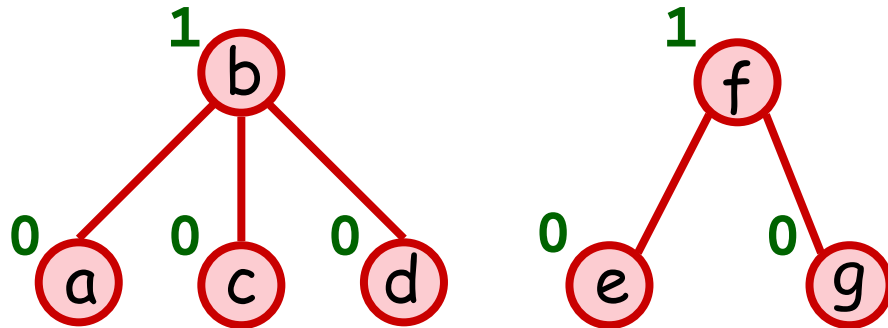
Union By Rank

- Rank needs **not** be very accurate
 - as long as it always gives an upper bound of height is enough
- When **Union** is performed, only the rank of the roots may change :
 - If both roots have same rank
 - rank of new root increases by 1
 - Else, no change

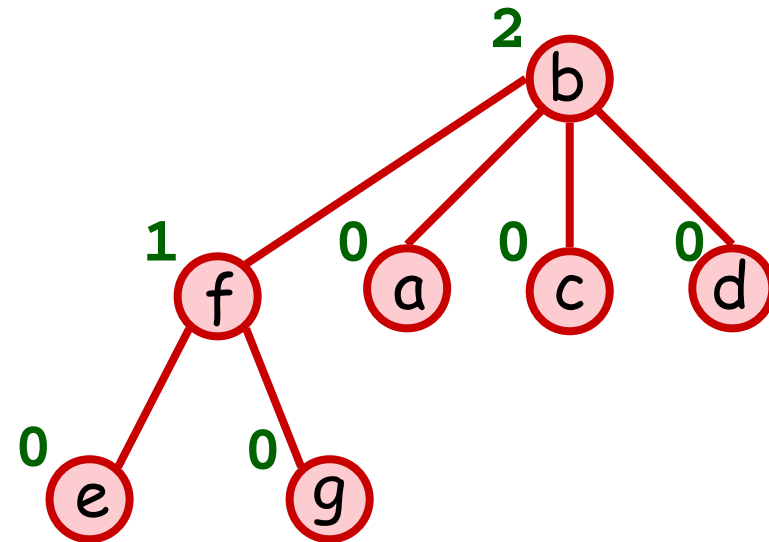
Example

? = rank

Before Union



After Union(c,f)



Union By Rank

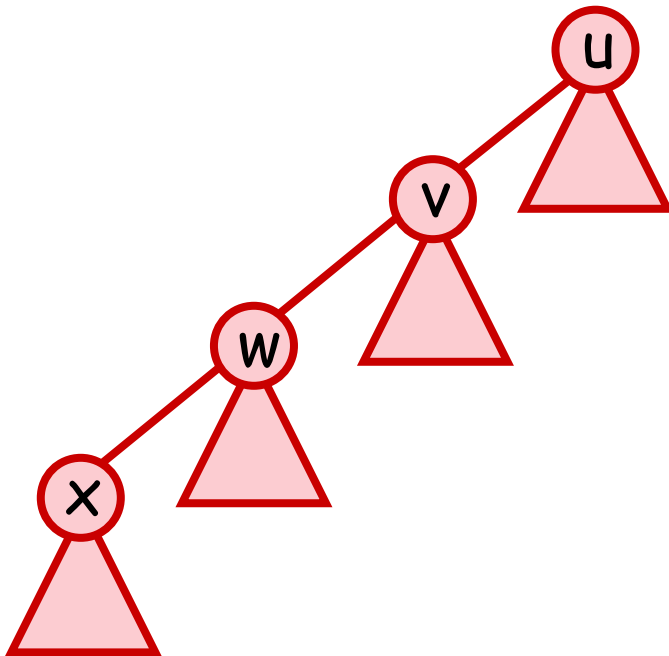
- Let H_{\max} = max height of all trees
 - $H_{\max} = O(\log n)$ (how to prove??)
 - m operations : $\Theta(m \log n)$ time
- So, union by rank is **no better** than union by size, but ...

Path Compression

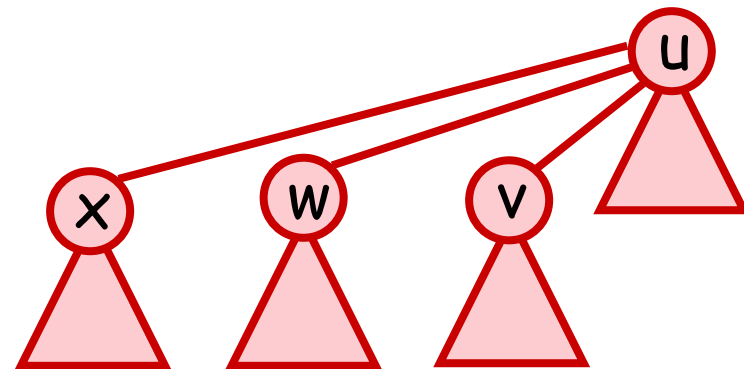
- The closer a node to its root, the faster the **Find** or **Union** operation
- When we perform **Find(x)**, we will need to find the root of the tree containing **x**
 - will access **every** ancestor of **x**
- why don't we make all these ancestors of **x** closer to the root now?
(Because no increase in asymptotic performance !!!)

Example

Before Find(x)



After Find(x)



Union by Rank + Path Compression

- With path compression, the more Find we have, the better its average performance

Fact: In the worst-case, m operations with f Find runs in $\Theta(m + f \log_{2+f/n} n)$ time

→ still no improvement in worst-case

- Interestingly, by combining union-by-rank (at Union) and path compression (at Find)

m operations: $\Theta(m \alpha(n))$ time

Inverse Ackermann
(in practice, at most 4)

Finding Connected Components

- Recall: To find connected components of a graph G with n vertices and m edges
 - there are n Make-Set and m Find or Union operations
- Which scheme for dynamic disjoint sets gives the best running time (theoretically)?
Ans. Depends on m (why?)