

CS4311

Design and Analysis of Algorithms

Lecture 20:
Data Structures for Disjoint Sets I

About this lecture

- Data Structure for Disjoint Sets
 - Support Union and Find operations
- Various Methods:
 1. Linked List (this lecture)
 2. Union by Size
 3. Union by Rank
 4. Union by Rank + Path Compression

Maintaining Disjoint Set

- In some applications, especially in algorithms relating to graphs, we often have a set of elements, and want to maintain a **dynamic partition** of them
 - I.e., the partition changes over time
- Our target corresponds to maintaining **dynamic disjoint sets** of the elements

Maintaining Disjoint Set

- Let $\Sigma = \{ S_1, S_2, \dots, S_k \}$ be a collection of dynamic disjoint sets of the elements
- Let x and y be any two elements
- We want to support:

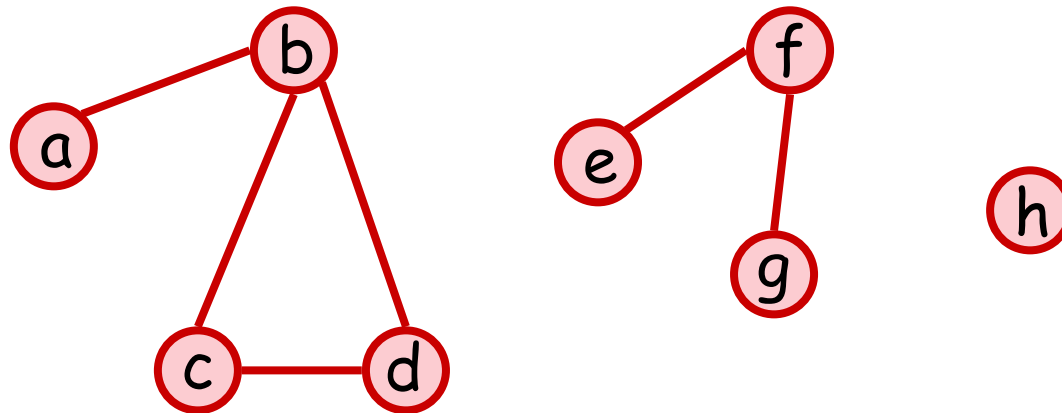
Make-Set(x): create a set containing x

Find(x): return which set x belongs

Union(x, y): merge the sets containing x and containing y into one

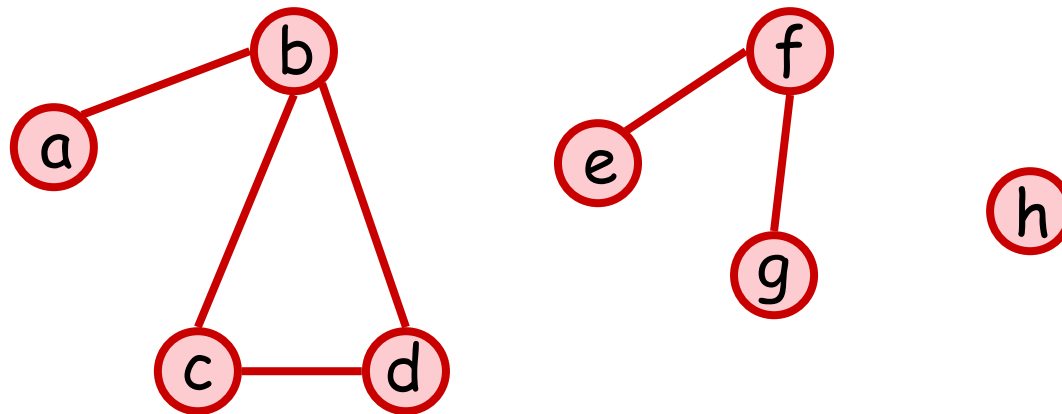
Example Application: Finding Connected Components

Step 0: Begin with the input graph



Example Application: Finding Connected Components

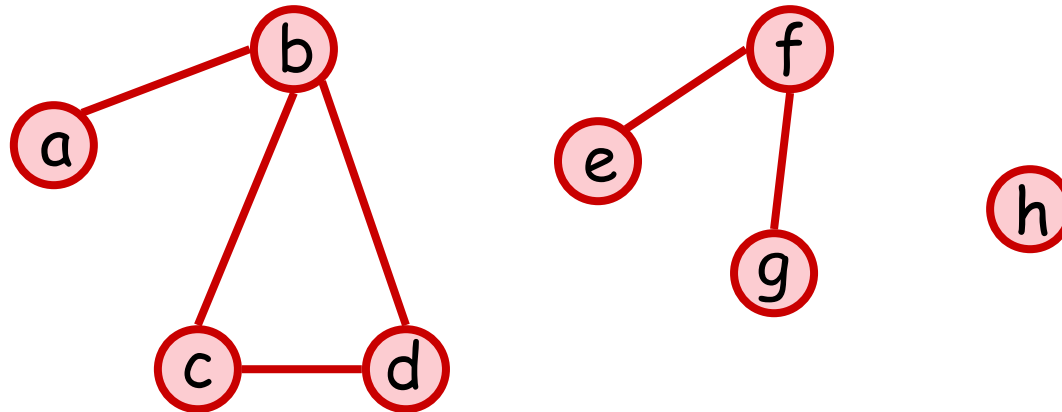
Step 1: *Make-Set*(v) for each vertex v



current Σ : $\{ \{a\}, \{b\}, \{c\}, \{d\}, \{e\}, \{f\}, \{g\}, \{h\} \}$

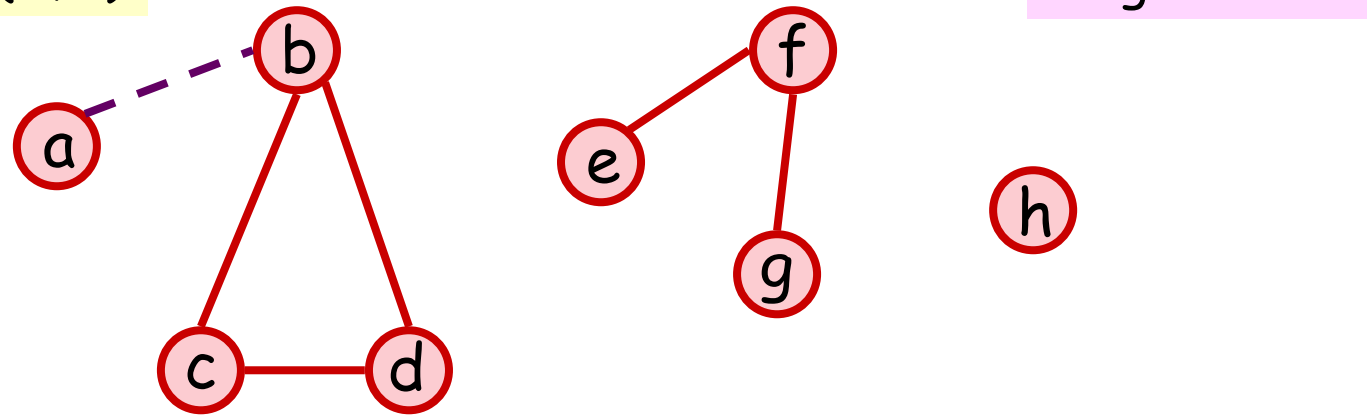
Example Application: Finding Connected Components

Step 2: Visit each edge (u,v) , perform $\text{Union}(u,v)$



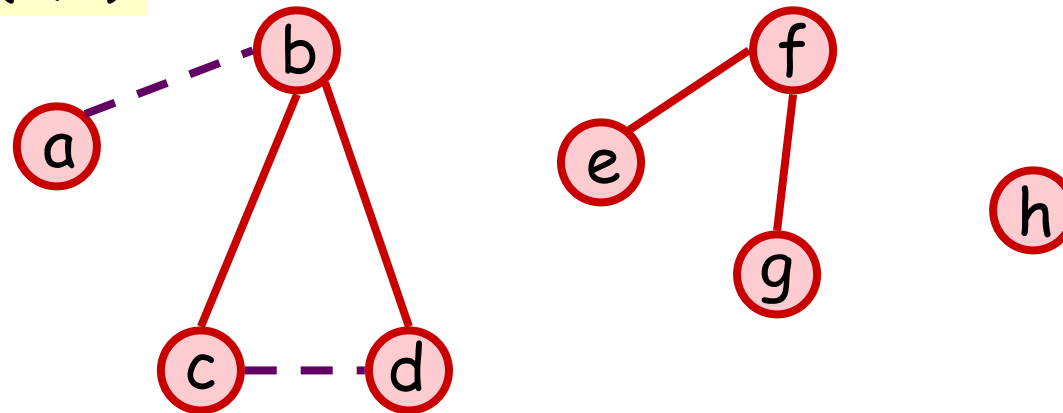
current Σ : $\{ \{a\}, \{b\}, \{c\}, \{d\}, \{e\}, \{f\}, \{g\}, \{h\} \}$

Step 2: Visit (a,b)



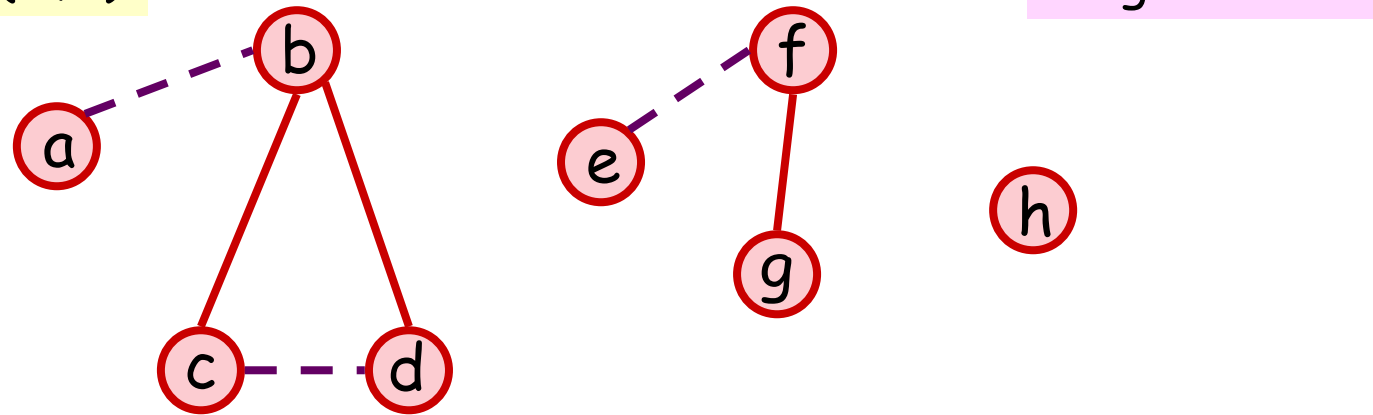
current Σ : { {a,b}, {c}, {d}, {e}, {f}, {g}, {h} }

Step 2: Visit (c,d)



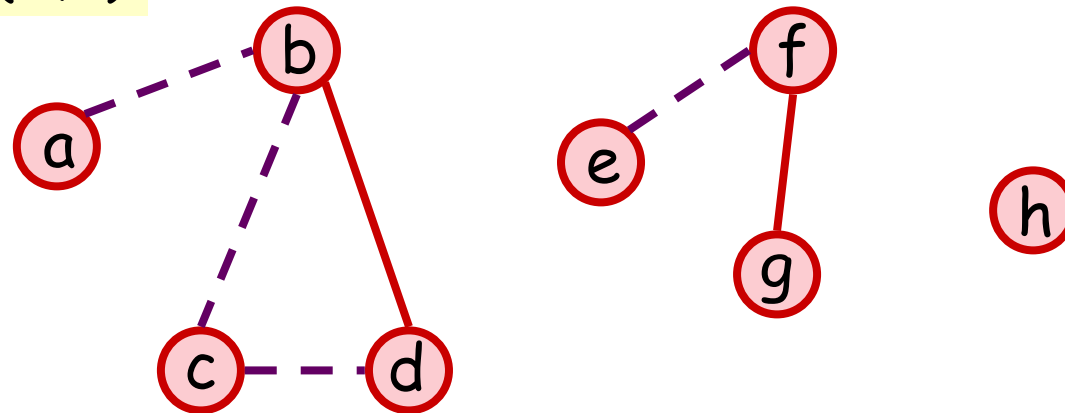
current Σ : { {a,b}, {c,d}, {e}, {f}, {g}, {h} }

Step 2: Visit (e,f)



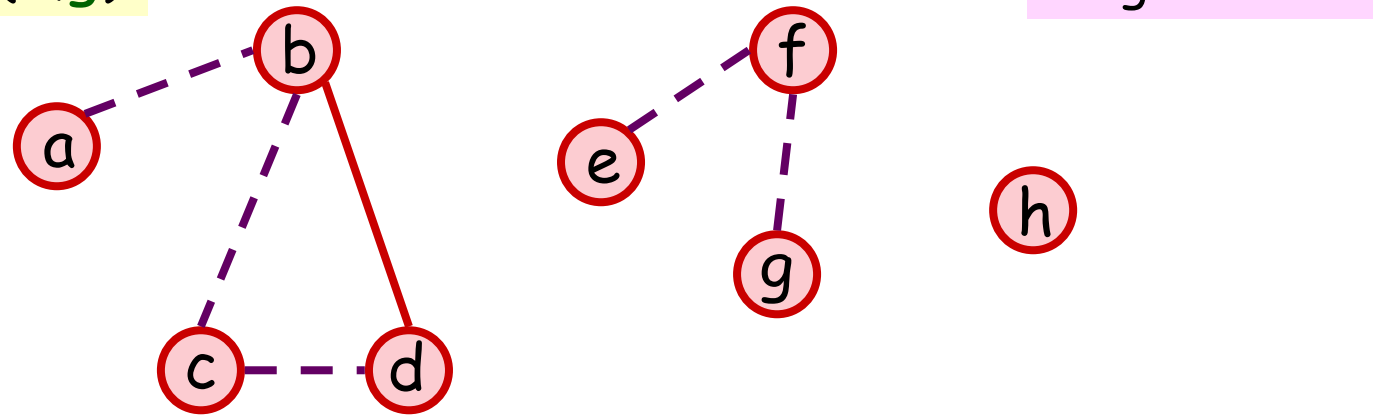
current Σ : $\{ \{a,b\}, \{c,d\}, \{e,f\}, \{g\}, \{h\} \}$

Step 2: Visit (b,c)



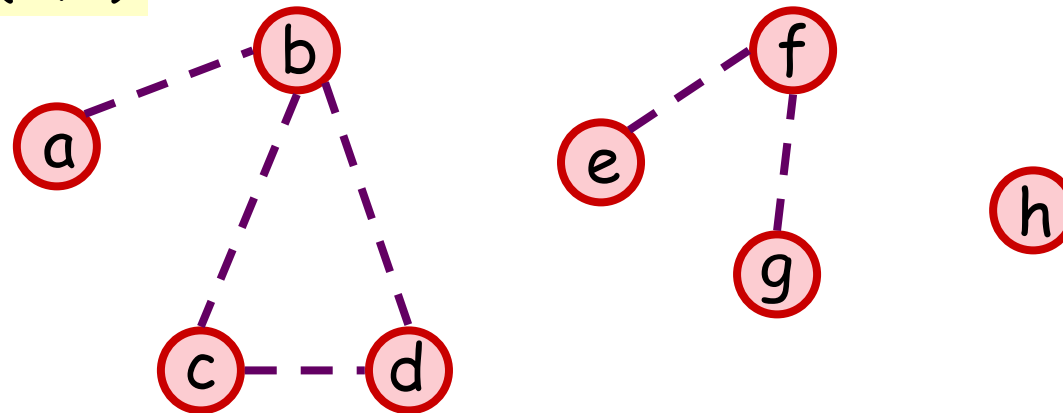
current Σ : $\{ \{a,b,c,d\}, \{e,f\}, \{g\}, \{h\} \}$

Step 2: Visit (f,g)



current Σ : $\{ \{a,b,c,d\}, \{e,f,g\}, \{h\} \}$

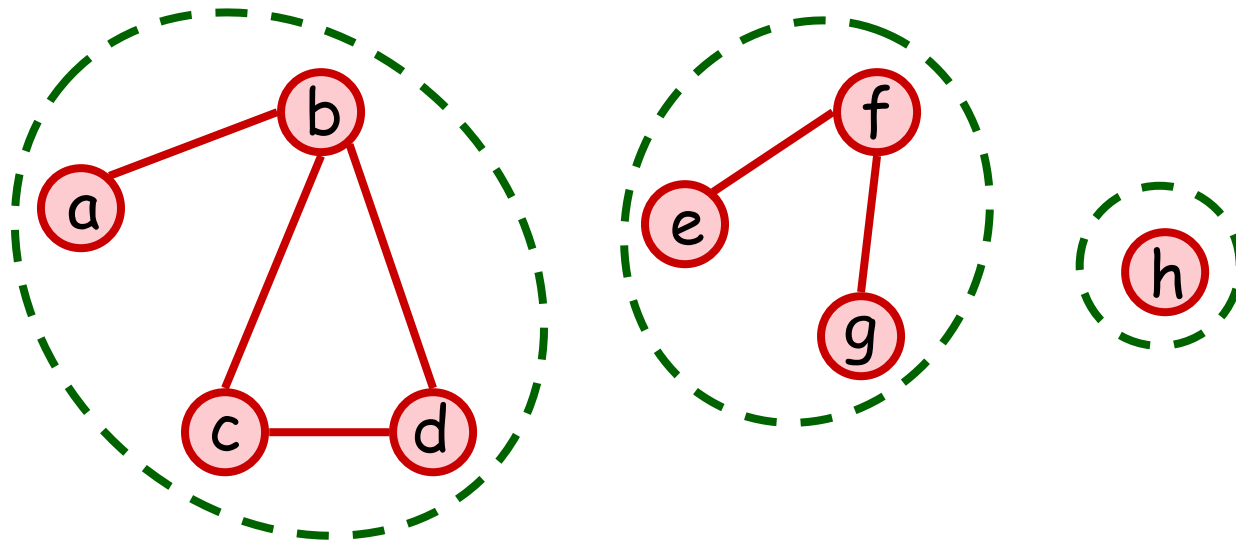
Step 2: Visit (b,d)



current Σ : $\{ \{a,b,c,d\}, \{e,f,g\}, \{h\} \}$

Example Application: Finding Connected Components

After Step 2 (when all edges visited) :
Each Disjoint Set \leftrightarrow Connected Component



current Σ : $\{ \{a,b,c,d\}, \{e,f,g\}, \{h\} \}$

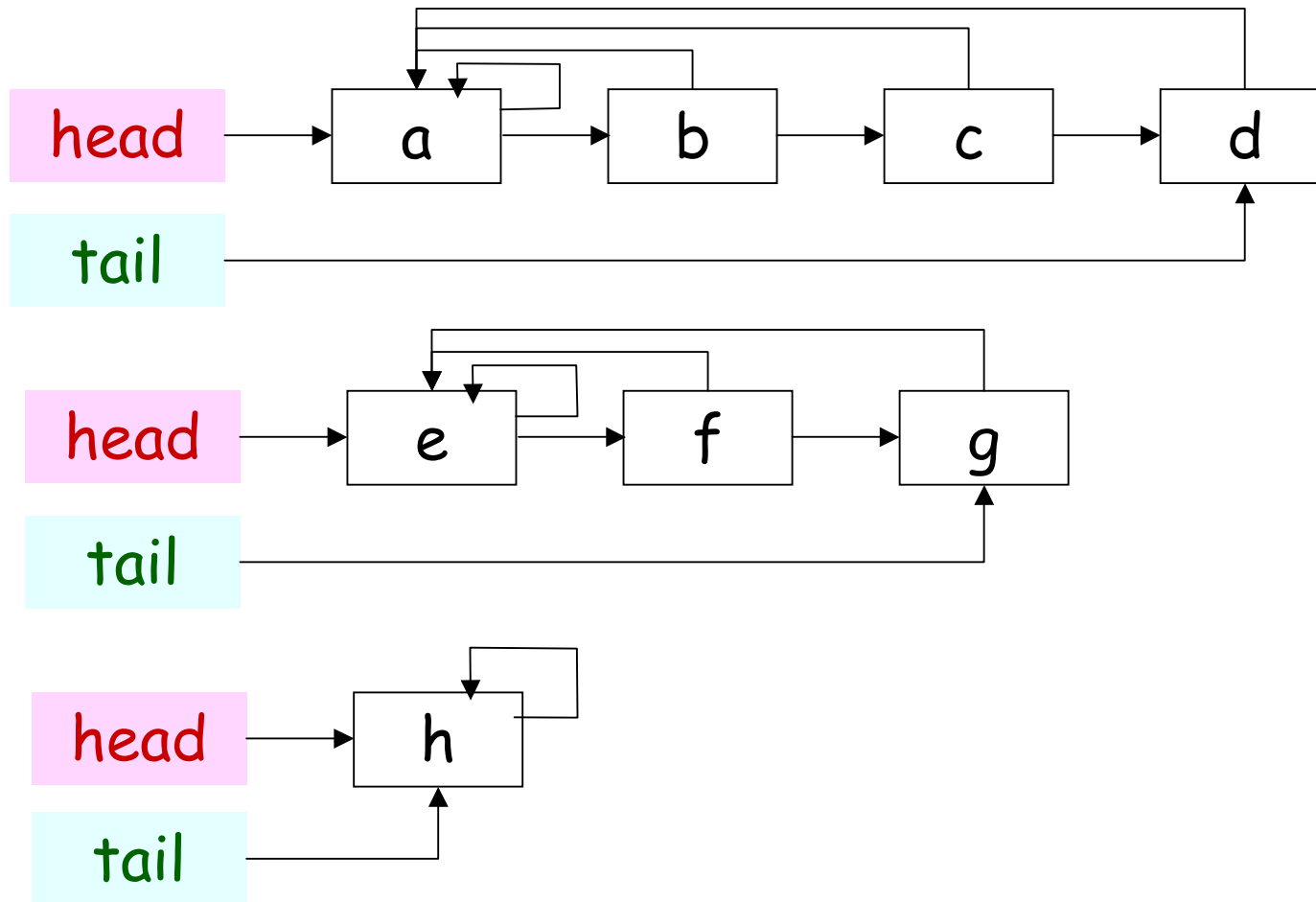
Remarks

- To facilitate $\text{Find}(x)$, each set usually chooses one of its element as a **representative**
 - $\text{Find}(x)$ returns the representative element of the set where x belongs
- To check if x and y belong to the same set, we can just check if
$$\text{Find}(x) == \text{Find}(y)$$

Disjoint Set with Linked List

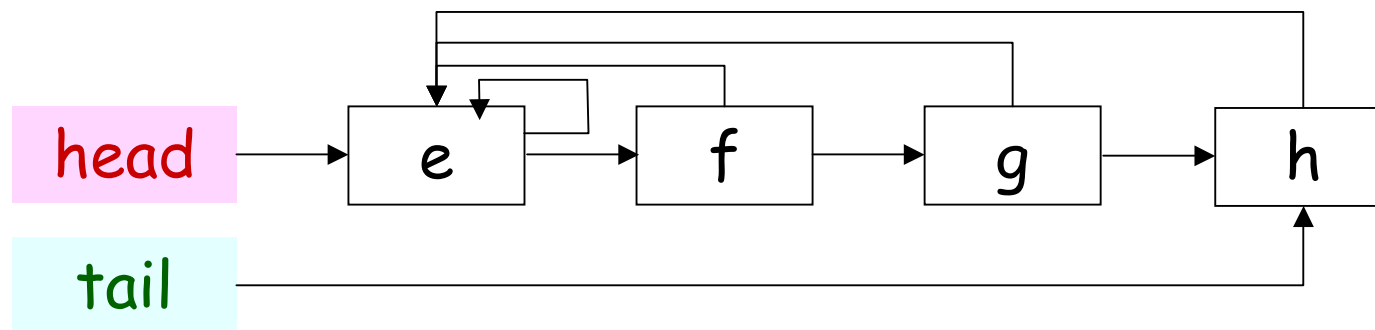
- A simple way to maintain disjoint sets is by using **linked lists**:
 - Each set \Leftrightarrow a **separate** linked list
 - Representative \Leftrightarrow **head** element of list
- To facilitate **Find** and **Union**:
 - each element in the list has an extra pointer that points at **head** element
 - each list has a pointer to the **tail**

E.g., disjoint sets $\{ \{a,b,c,d\}, \{e,f,g\}, \{h\} \}$
is stored by:



Disjoint Set with Linked List

- To perform $\text{Union}(x,y)$, we join the lists containing x and containing y , one list after the other, and update the pointers of the latter list
- E.g. $\text{Union}(g,h)$ in previous example gives:



Disjoint Set with Linked List

- In the worst-case:
 - Make-Set or Find : $\Theta(1)$ time
 - Union : $\Theta(n)$ time
- m operations on n elements :
 $\Theta(m + n^2)$ time

Disjoint Set with Linked List

- Let us apply a **weighted-union heuristic** :
To perform **Union**, we merge lists with longer one first, followed by shorter list
- No change in worst-case time, but ...
- **m** operations : $\Theta(m + n \log n)$ time

Reason: The time to perform **Union** is from changing **head** pointer of each element in the latter list
With the heuristic, each element changes **head** pointer at most **$\log n$** times (why??)