CS5321 Numerical Optimization Homework 3 Line Search and Multi-dimensional Problems Due April 5, 2012

1. (40%) Recall the Wolfe conditions for step length α

- Sufficient decrease cond: $f(x_k + \alpha p_k) \leq f(x_k) + c_1 \alpha f'(x_k) p_k$,
- Curvature condition: $f'(x_k + \alpha p_k)p_k \ge c_2 f'(x_k)p_k$,

for $0 < c_1 < c_2 < 1$ and $p_k = \pm 1$. Suppose function f is Lipschitz continuous, which means

$$|f'(x) - f'(y)| \le L|x - y|$$
 for all x, y and $L > 0$.

Prove the following results.

- (a) The curvature condition implies $\alpha \geq \frac{(c_2 1)f'(x_k)p_k}{L} > 0$. In other word, the curvature condition enforces α not too small.
- (b) Let $x_{k+1} = x_k + \alpha_k p_k$. The sufficient decrease condition, with the result of (a), implies

$$f(x_k) - f(x_{k+1}) \ge \frac{c_1(1-c_2)}{L} |f'(x_k)|^2 > 0.$$

This means the sufficient decrease condition ensures the *sufficient* decrease of function value.

(c) Suppose f is bounded below, which means $f(x_0) - f(x_k)$ is smaller than some positive constant for all k. Show

$$\sum_{k=0}^{\infty} |f'(x_k)|^2 < \infty.$$

2. (60%) Let $f(x,y) = \frac{1}{2}(x-1)^2 + \frac{9}{2}(y-1)^2$. This is a positive definite quadratic with minimizer at $(x^*, y^*) = (1, 1)$.

- (a) Derive the gradient g and the Hessian H of f.
- (b) Write Matlab codes to implement the steepest descent method and Newton's method with $\vec{x}_0 = (9, 0)$, and compare their convergent results. The formula of the steepest descent method is

$$\vec{x}_{k+1} = \vec{x}_k - \frac{\vec{g}_k^T \vec{g}_k}{\vec{g}_k^T H_k \vec{g}_k} \vec{g}_k,$$

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and the formula of Newton's method is

$$\vec{x}_{k+1} = \vec{x}_k - H_k^{-1} \vec{g}_k,$$

where $\vec{g}_k = g(\vec{x}_k)$ and $H_k = H(\vec{x}_k)$.

- *** In Matlab, use x=A\b to compute $x = A^{-1}b$.
- (c) Draw the trace of $\{\vec{x}_k\}$ for the steepest descent method and Newton's method. An example code for trace drawing is given as follows.

```
function draw_trace()
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% draw the contour of the function z = ((x-1)^2+9*(y-1)^2)/2;
step = 0.1;
X = 0:step:9;
Y = -1:step:1;
n = size(X,2);
m = size(Y,2);
Z = zeros(m,n);
for i = 1:n
   for j = 1:m
      Z(j,i) = f(X(i),Y(j));
   end
end
contour(X,Y,Z,100)
% function definition
    function z = f(x, y)
        z = 1/2*(x-1)^2+9/2*(y-1)^2;
    end
end
```