CS3331 Numerical Methods

Quiz 6, Dec 12

Name: _____, ID: _____

Decompose $\mathbf{A} = \mathbf{L} + \mathbf{D} + \mathbf{U}$, where \mathbf{L} is the lower triangular part; \mathbf{D} is the diagonal part; and \mathbf{U} is the upper triangular part. The formulas of three iterative methods are

- Jacobi method: $\mathbf{x}^{(k+1)} = \mathbf{D}^{-1}(-\mathbf{L} \mathbf{U})\mathbf{x}^{(k)} + \mathbf{D}^{-1}\mathbf{b}$
- Gauss-Seidel method: $\mathbf{x}^{(k+1)} = -(\mathbf{D} + \mathbf{L})^{-1}\mathbf{U}\mathbf{x}^{(k)} + (\mathbf{D} + \mathbf{L})^{-1}\mathbf{b}$
- Successive over relaxation (SOR): $\mathbf{x}^{(k+1)} = (\mathbf{D} + \omega \mathbf{L})^{-1} \left[((1-\omega)\mathbf{D} \omega \mathbf{U})\mathbf{x}^{(k)} + \omega \mathbf{b} \right]$
- 1. True or false. (20pt)
 - a (F) The diagonal elements of $D^{-1}(-L U)$ are the reciprocals of A's diagonal elements.
 - b (F) The eigenvalues of a strictly diagonal dominant matrix are all positive.
 - c (T) The eigenvalues of a symmetric positive definite matrix are all positive.
 - d (F) If $\|\mathbf{D}^{-1}(-\mathbf{L}-\mathbf{U})\| > 1$, then Jacobi method cannot converge.
 - e (T) If A is symmetric and strictly diagonal dominant, then Gauss-Seidel method guarantees convergence.
 - f (F) Gauss-Seidel method always converges faster than Jacobi method.
 - g (T) The determinant of $(\mathbf{D} + \mathbf{L})^{-1}\mathbf{U}$ equals to 0.
 - h (F) In SOR, $0 < \omega < 2$ can guarantee the convergence.
 - i (**T**) The determinant of $(\mathbf{D} + \omega \mathbf{L})^{-1}((1-\omega)\mathbf{D} \omega \mathbf{U})$ is $(1-\omega)^n$, where *n* is the size of **A**.
 - j (F) The spectral radius of \mathbf{A} is the largest singular value of \mathbf{A} .

2. The new vector of SOR $\mathbf{x}^{(k+1)}$ is a linear combination of the previous one $\mathbf{x}^{(k)}$ and the vector generated by Gauss-Seidel.

$$\mathbf{x}^{(k+1)} = (1-\omega)\mathbf{x}^{(k)} + \omega[-\mathbf{D}^{-1}\mathbf{L}\mathbf{x}^{(k+1)} - \mathbf{D}^{-1}\mathbf{U}\mathbf{x}^{(k)} + \mathbf{D}^{-1}\mathbf{b}].$$

Prove that $\mathbf{x}^{(k+1)} = (\mathbf{D} + \omega \mathbf{L})^{-1} \left[((1-\omega)\mathbf{D} - \omega \mathbf{U})\mathbf{x}^{(k)} + \omega \mathbf{b} \right]$. (10pt) (No partial credits. Giving up or leaving it blank get 3 points.)

$$\begin{aligned} \mathbf{x}^{(k+1)} &= (1-\omega)\mathbf{x}^{(k)} + \omega[-\mathbf{D}^{-1}\mathbf{L}\mathbf{x}^{(k+1)} - \mathbf{D}^{-1}\mathbf{U}\mathbf{x}^{(k)} + \mathbf{D}^{-1}\mathbf{b}] \\ \mathbf{D}^{-1}(\mathbf{D} + \omega\mathbf{L})\mathbf{x}^{(k+1)} &= [(1-\omega)\mathbf{I} - \omega\mathbf{D}^{-1}\mathbf{U}]\mathbf{x}^{(k)} + \omega\mathbf{D}^{-1}\mathbf{b} \\ (\mathbf{D} + \omega\mathbf{L})\mathbf{x}^{(k+1)} &= [(1-\omega)\mathbf{D} - \omega\mathbf{U}]\mathbf{x}^{(k)} + \omega\mathbf{b} \\ \mathbf{x}^{(k+1)} &= (\mathbf{D} + \omega\mathbf{L})^{-1}\left[((1-\omega)\mathbf{D} - \omega\mathbf{U})\mathbf{x}^{(k)} + \omega\mathbf{b}\right] \end{aligned}$$

3. Let
$$\mathbf{A} = \begin{pmatrix} 2 & 1 & 0 & 1 \\ 0 & 2 & 0 & 1 \\ 1 & 0 & 2 & 0 \\ 1 & 0 & 1 & 2 \end{pmatrix}$$
, $\mathbf{b} = \begin{pmatrix} 0 \\ 2 \\ 0 \\ 2 \end{pmatrix}$ and $\mathbf{x}^{(0)} = \begin{pmatrix} 6 \\ 0 \\ 2 \\ 4 \end{pmatrix}$. Use Gauss-Seidel method to compute $\mathbf{x}^{(1)}$ (20pt)

Seidel method to compute $\mathbf{x}^{(1)}$. (20pt)

$$\begin{aligned} x_1^{(1)} &= -1/2 * 0 - 1/2 * 4 + 0/2 &= -2 \\ x_2^{(1)} &= 0/2 * (-2) - 1/2 * 4 + 2/2 &= -1 \\ x_3^{(1)} &= -1/2 * (-2) + 0/2 &= 1 \\ x_4^{(1)} &= -1/2 * (-2) - 1/2 * 1 + 2/2 &= 1.5 \\ \mathbf{x}_4^{(1)} &= -1/2 * (-2) - 1/2 * 1 + 2/2 &= 1.5 \\ \mathbf{x}_4^{(1)} &= \begin{pmatrix} x_1^{(1)} \\ x_2^{(1)} \\ x_3^{(1)} \\ x_4^{(1)} \end{pmatrix} = \begin{pmatrix} -2 \\ -1 \\ 1 \\ 1.5 \end{pmatrix} \end{aligned}$$