

H1 : Linear Systems of Equations

(1) Let $A = \begin{bmatrix} 3 & 0 \\ -1 & 2 \\ 1 & 1 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 4 & 2 \\ 3 & 1 & 5 \end{bmatrix}$.

(a) Find AB and BA .

(b) Find $(BA)^t$ and $A^t B^t$.

(c) Find $(BA)^{-1}$. Can you find $(AB)^{-1}$?

(2) A linear system of equations is given below.

$$2x - 2y + 3z = 5$$

$$-2x + 3y - 4z = -6$$

$$4x - 3y + 7z = 11$$

(a) Write this equation as $A\mathbf{x} = \mathbf{b}$, where $\mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$

(b) What is the augmented matrix for this system?

(c) Apply Gaussian elimination and back substitution to solve $A\mathbf{x} = \mathbf{b}$.

(d) Find $A = LU$, where L is unit lower- Δ and U is upper- Δ .

(3) Let $\mathbf{e}_j \in R^n$ be a unit vector with j -th component 1 and 0 otherwise, e.g., $\mathbf{e}_2 = [0, 1, 0]^t$ for $n = 3$. Let the matrices P, Q, R be defined as

$$P = I + 2\mathbf{e}_2\mathbf{e}_1^t, \quad Q = I - 3\mathbf{e}_3\mathbf{e}_1^t, \quad R = I + 4\mathbf{e}_3\mathbf{e}_2^t.$$

(a) Compute P^{-1} , Q^{-1} , and R^{-1} .

(b) Compute $R^{-1}Q^{-1}P^{-1}$ and $(RQP)^{-1}$, respectively.

(4) Given

$$A = \begin{bmatrix} 2 & 1 & 3 \\ 4 & 2 & 7 \\ 1 & 3 & 5 \end{bmatrix}, \quad B = \begin{bmatrix} 2 & 1 & 3 \\ 0 & 0 & 1 \\ 1 & 3 & 5 \end{bmatrix}, \quad C = \begin{bmatrix} 0 & 1 & 3 \\ 0 & 2 & 7 \\ -5 & 3 & 5 \end{bmatrix}.$$

(a) Find an elementary matrix E such that $EA = B$.

(b) Find an elementary matrix F such that $AF = C$.

(5) A linear system of equations is given below.

$$x + y = 1$$

$$x + y + 2z = 3$$

$$2x + y - 2z = 0$$

(a) Write this equation as $A\mathbf{x} = \mathbf{b}$, where $\mathbf{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$

(b) What is the augmented matrix for this system?

(c) Apply Gaussian elimination with Partial Pivoting, followed by back substitution to solve $A\mathbf{x} = \mathbf{b}$.

(d) Find a permutation matrix P such that $PA = LU$, where L is unit lower- Δ and U is upper- Δ .

(6) Give the following Matlab code.

```
A=[1, 2, 3; 2, 6, 10; 3, 14, 28];
b=[1; 0; -8];
format short
X=A\b
```

- (a) Find the *LU-decomposition* for A .
 - (b) What does the above Matlab code do?
 - (c) What is the output of X ?
- (7) Suppose that a *tridiagonal matrix* $T \in R^{n \times n}$ is also diagonally dominant.
- (a) Give an efficient algorithm to do $T = LU$.
 - (b) How many floating-point operations (flops) are needed for your algorithm?
- (8) Let $C, D \in R^{n \times n}$ be invertible. prove the following equalities (Exercise 243 on P.87).
- (a) $(C^{-1} + D^{-1})^{-1} = C(C + D)^{-1}D$
 - (b) $(I + CD)^{-1}C = C(I + DC)^{-1}$
 - (c) $(C + DD^t)^{-1}D = C^{-1}D(I + D^tC^{-1}D)^{-1}$

Solutions for Exercise 1

$$(1) \quad A = \begin{bmatrix} 3 & 0 \\ -1 & 2 \\ 1 & 1 \end{bmatrix}, B = \begin{bmatrix} 1 & 4 & 2 \\ 3 & 1 & 5 \end{bmatrix}.$$

$$(a) \quad AB = \begin{bmatrix} 3 & 12 & 6 \\ 5 & -2 & 8 \\ 4 & 5 & 7 \end{bmatrix}, \quad BA = \begin{bmatrix} 1 & 10 \\ 13 & 7 \end{bmatrix}$$

$$(b) \quad (BA)^t = \begin{bmatrix} 1 & 13 \\ 10 & 7 \end{bmatrix}, \quad A^t B^t = (BA)^t, \quad (c) \quad (BA)^{-1} = \frac{1}{123} \begin{bmatrix} -7 & 10 \\ 13 & -1 \end{bmatrix}, \quad (AB)^{-1}$$

does not exist.

(2) A linear system of equations is given below.

$$2x - 2y + 3z = 1$$

$$-2x + 3y - 4z = 0$$

$$4x - 3y + 7z = 5$$

$$(a) \quad \begin{bmatrix} 2 & -2 & 3 \\ -2 & 3 & -4 \\ 4 & -3 & 7 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 5 \end{bmatrix}, \quad (b) \quad \begin{bmatrix} 2 & -2 & 3 & | & 1 \\ -2 & 3 & -4 & | & 0 \\ 4 & -3 & 7 & | & 5 \end{bmatrix}$$

$$(d) \quad LU = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & -2 & 3 \\ 0 & 1 & -1 \\ 0 & 0 & 2 \end{bmatrix} \Rightarrow (c) \quad \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

- (3) Let $\mathbf{e}_j \in R^n$ be a unit vector with j -th component 1 and 0 otherwise, e.g., $\mathbf{e}_2 = [0, 1, 0]^t$ for $n = 3$. Let the matrices P, Q, R be defined as

$$P = I + 2\mathbf{e}_2\mathbf{e}_1^t, \quad Q = I - 3\mathbf{e}_3\mathbf{e}_1^t, \quad R = I + 4\mathbf{e}_3\mathbf{e}_2^t$$

$$(a) \quad P^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad Q^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}, \quad R^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -4 & 1 \end{bmatrix}$$

$$(b) \quad R^{-1}Q^{-1}P^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 11 & -4 & 1 \end{bmatrix}, \quad P^{-1}Q^{-1}R^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -4 & 1 \end{bmatrix}$$

$$(c) \quad P = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad Q = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}, \quad R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 4 & 1 \end{bmatrix}$$

(4)

$$E = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad F = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

5 $\mathbf{x} = [1, 0, 1]^t$.

Matlab Solutions

(1)

```
A=[ 3, 0; -1, 2; 1, 1];
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B=[ 1, 4, 2; 3, 1, 5];
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(a) $AB=A*B$, $BA=B*A$

(b) $BA^t=(B*A)'$

(c) $BA_{inv}=inv(BA)$

(3) $e1=[1, 0, 0]'$;

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e2=[0, 1, 0]';
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e3=[0, 0, 1]';
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(a) $P_{inv}=inv(P)$, $Q_{inv}=inv(Q)$, $R_{inv}=inv(R)$

(b) $R_{inv}*Q_{inv}*P_{inv}$; $P_{inv}*Q_{inv}*R_{inv}$

(c) $P=eye(3)+2*e2*e1'$

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Q=eye(3)-3*e3*e1'
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R=eye(3)+4*e3*e2'
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(d) $PQR_{inv}=inv(P*Q*R)$

(5) $A=[1,1,0; 1,1,2; 2,1,-2]$;

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b=[1;3;0];
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```
x=A\b
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```
so x=[1, 0, 1]'
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