

Introduction

- The central problems of Linear Algebra are to study the properties of matrices and to investigate the solutions of systems of linear equations
- Given A and b , find x for $Ax=b$; i.e., solve $Ax=b$
- Given A , find λ (**lambda**) such that $Ax=\lambda x$

Matrices and Linear Systems of Equations

- Matrix notations and operations
- Elementary row operations
- Row-echelon form
- Matrix inverse
- LU-Decomposition for Invertible Matrices
- LU-Decomposition with Partial Pivoting
- Some special matrices

Determinants

- Definition of Determinant $\det(A)$ or $|A|$
- Cofactor and minor at (i,j) -position of A
- Properties of determinants
- Examples and Applications

Vector Space and Linear Transform

- Vector Space, Subspace, Examples
- Null space, column space, row space of a matrix
- Spanning sets, Linear Independence, Basis, Dimension
- Rank, Nullity, and the Fundamental Matrix Spaces
- Matrix Transformation from \mathbb{R}^n to \mathbb{R}^m
- Kernel and Image of a Linear Transform
 - Projection, rotation, scaling
 - Gauss transform
 - Householder transform (elementary reflector)
 - Jacobi transform (Givens' rotation)
- An affine transform is in general not a linear transform

Orthogonality

- Motivation – More intuitive
- Inner product and projection
- Orthogonal vectors and linear independence
- Orthogonal complement
- Projection and least squares approximation
- Orthonormal bases and orthogonal matrices
- Gram-Schmidt orthogonalization process
- QR factorization

Eigenvalues and Eigenvectors

- Definitions and Examples
- Properties of eigenvalues and eigenvectors
- Diagonalization of matrices
- Similarity transformation and triangularization
 - Positive definite (Semi-definite) matrices
- Spectrum decomposition
- Singular Value Decomposition (SVD)
- A Markov process
- Differential equations and $\exp(A)$
- Algebraic multiplicity and geometric multiplicity
- Minimal polynomials and Jordan blocks