

# Chapter 1

## Introduction

The *Blue Moon Rendering Tools* (BMRT) are a collection of programs that render 3-D scene models.

BMRT uses some APIs that are very similar to those described in the published RenderMan Interface Specification. However, BMRT is not associated with Pixar, and no claims are made that BMRT is in any way a compatible replacement for RenderMan. Those who want a licensed implementation of RenderMan should contact Pixar directly.

Despite these technical/legal terms, you may find that most applications, scene files, and shaders written to conform to the RenderMan Interface can also use BMRT without modification.

This document is intended for the reader who is familiar with the concepts of computer graphics and already is fluent in both the RenderMan procedural interface and the RIB archival format (due to BMRT's similarities to that published specification). For more detailed information about the RenderMan standard, we recommend *Advanced RenderMan: Creating CGI for Motion Pictures* by Anthony Apodaca and Larry Gritz, *The RenderMan Companion* by Steve Upstill, or the official RenderMan Interface Specification, available from Pixar. All of these texts are fully detailed and clearly written, and no attempt will be made here to duplicate the information in these references.

The parts of BMRT you'll most likely use are outlined below:

***rgl*** A previewer for RIB files which runs on top of OpenGL. Primitives display as lines or Gouraud-shaded polygons.

***rendrib*** A high quality renderer which uses some of the latest techniques of radiosity and ray tracing to produce near photorealistic images.

***slc*** A compiler for shaders, allowing you to write your own procedures for defining the appearance of surfaces, lights, displacements, volume attenuation, and pixel operations.

***mkmip*** A program to pre-process texture, shadow, and environment map files for more efficient access during rendering.

```

                                colorspheres.c
/*
  SGI:
    cc -n32 -I../include colorspheres.c -L../lib -lribout -o colorspheres

  Linux:
    cc -I../include colorspheres.c -L../lib -lribout -o colorspheres

  Win32:
    cl /I..\include /c colorspheres.c
    link colorspheres.obj ..\lib\libribout.lib /out:colorspheres.exe
*/

#include <stdlib.h>
#include <stdio.h>
#include <string.h>
#include <ri.h>

#define NFRAMES 100
#define NSPHERES 4
#define FRAMEROT 15.0f

void
ColorSpheres(int n, float s)
{
    int x, y, z;
    RtColor color;

    if(n <= 0) {
        return;
    }

    RiAttributeBegin();

    RiTranslate(-0.5f, -0.5f, -0.5f );
    RiScale(1.0f/n, 1.0f/n, 1.0f/n);

    for (x = 0; x < n; x++) {
        for (y = 0; y < n; y++) {
            for (z = 0; z < n; z++) {
                color[0] = ((float) x+1) / ((float) n);
                color[1] = ((float) y+1) / ((float) n);
                color[2] = ((float) z+1) / ((float) n);

                RiColor(color);
                RiTransformBegin();
                RiTranslate(x+.5f, y+.5f, z+.5f);
                RiScale(s, s, s);
                RiSphere(0.5f, -0.5f, 0.5f, 360.0f, RI_NULL);
                RiTransformEnd();
            }
        }
    }

    RiAttributeEnd();

    return ;
}

int main(int argC, char** argV)
{
    RtInt   frame;
    float   scale;
    char    filename[64];
    char*   renderer = RI_NULL;

```

```

                                colorspheres.c
if (argC != 2) {
    fprintf(stderr,
        "USAGE: %s ribFile|rgl|rendrib\n\n",
        argv[0]);
    exit (-1);
}

renderer = argv[1];

/* if the variable renderer is "rgl" or "rendrib", RiBegin() will
   attempt to start up that renderer and pipe its output directly to
   that renderer.  Since RiDisplay is set to put its output to the
   framebuffer, that renderer will attempt to open the framebuffer
   and render directly to it.  If the variable renderer is set to
   some other value, RiBegin() will open that as a file and put the
   RIB commands in it.
*/

RiBegin(renderer);

for (frame = 0; frame <= NFRAMES; frame++) {
    sprintf(filename, "colorSpheres.%03d.tif", frame );
    RiFrameBegin(frame);

    RiProjection("perspective", RI_NULL);
    RiTranslate(0.0f, 0.0f, 1.5f);
    RiRotate(40.0f, -1.0f, 1.0f, 0.0f);

    RiDisplay(filename, RI_FRAMEBUFFER, RI_RGBA, RI_NULL);
    RiFormat((RtInt)256, (RtInt)192, -1.0f);
    RiShadingRate(1.0);

    RiWorldBegin();

    RiLightSource("distantlight", RI_NULL);

    RiSides((RtInt)1);

    scale = (float)(NFRAMES-(frame-1)) / (float)NFRAMES;
    RiRotate(FRAMEROT*frame, 0.0f, 0.0f, 1.0f);
    RiSurface("plastic", RI_NULL);
    ColorSpheres(NSPHERES, scale);
    RiWorldEnd();
    RiFrameEnd();
}

RiEnd();

return 1;
}

```

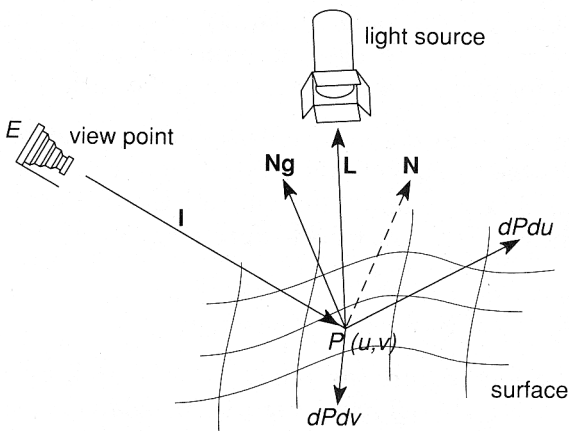


Figure 14.1 Surface position, normal, and parametric derivatives

## Surface position and change

The **point** value  $\underline{P}$  represents the position of the point being shaded in world space, and  $\underline{Ng}$  is the **geometric normal vector**, perpendicular to the surface, at that point. The **shading normal vector**  $\underline{N}$  is by default equal to  $\underline{Ng}$ , but may be different for shading purposes. If a displacement shader changes the surface normal, it usually works on  $\underline{N}$  and leaves  $\underline{Ng}$  alone.

## Parameter space

The floating-point values  $\underline{u}$  and  $\underline{v}$  give the position of the current point on the current surface in parameter space. The **points**  $\underline{dPdu}$  and  $\underline{dPdv}$  are parametric derivatives, giving the derivative of surface position  $\underline{P}$  with respect to  $\underline{u}$  and  $\underline{v}$ , respectively. The surface normal  $\underline{Ng}$  is defined to be the cross-product of these two vectors.  $\underline{u}$  and  $\underline{v}$  always range between exactly 0 and 1 on all surfaces except polygons.

Figure 14.1 illustrates  $\underline{P}$ ,  $\underline{Ng}$ ,  $\underline{dPdu}$  and  $\underline{dPdv}$ . The normal vector  $\underline{Ng}$  is the cross product of  $\underline{dPdu}$  and  $\underline{dPdv}$  by definition.

## Texture space

The floating-point values  $\underline{s}$  and  $\underline{t}$  give the texture-space coordinates of the current point on the surface. They may be used to

Table 14.2 lists each predefined global variable available to surface shaders, together with its data type, storage class and a summary of its meaning. Different sets of global variables are available to other shader types. They appear in Table 14.3.

Type	Name	Storage Class	Purpose
color	<u>Cs</u>	varying/uniform	Surface color (input)
color	<u>Os</u>	varying/uniform	Surface opacity (input)
point	<u>P</u>	varying	Surface position
point	<u>dPdu</u>	varying	Change in position with <i>u</i>
point	<u>dPdv</u>	varying	Change in position with <i>v</i>
point	<u>N</u>	varying	Surface shading normal
point	<u>Ng</u>	varying/uniform	Surface geometric normal
float	<u>u,v</u>	varying	Surface parameters
float	<u>du,dv</u>	varying/uniform	Change in <i>u,v</i> across element
float	<u>s,t</u>	varying	Surface texture coordinates
color	<u>L</u>	varying/uniform	Direction from surface to light source
color	<u>Cl</u>	varying/uniform	Light color
point	<u>I</u>	varying	Direction of ray impinging on surface point (often from camera)
color	<u>Ci</u>	varying	Color of light from surface (output)
color	<u>Oi</u>	varying	Opacity of surface (output)
point	<u>E</u>	uniform	Position of the camera

Table 14.2 Global Variables Available to Surface Shaders

## Surface color and transparency

Cs and Os represent the current surface color and opacity, respectively, as declared in **RiColor()** and **RiOpacity()** and bound to the surface being shaded when it was created.

Cs and Os are used as filter values. The color of reflected light from a surface with surface color Cs under incident light with color Cl is often taken to be  $\underline{Cl} * \underline{Cs}$ . In other words, each component of Cs scales the corresponding component of the incoming light according to the absorption of the surface. Os has the same effect on light passing *through* the surface. Normally, every component of Cs and Os lies in the range [0,1].

# Geometric Functions

The shading language defines a variety of functions for geometric calculations. These are summarized in Table 15.2 and discussed below.

Return Type	Declaration	Meaning
float	<b>xcomp</b> ( <i>P</i> )	return <i>x</i> component of <b>point</b> <i>P</i>
float	<b>ycomp</b> ( <i>P</i> )	return <i>y</i> component of <b>point</b> <i>P</i>
float	<b>zcomp</b> ( <i>P</i> )	return <i>z</i> component of <b>point</b> <i>P</i>
—	<b>setxcomp</b> ( <i>P</i> , <i>v</i> )	set <i>x</i> component of <b>point</b> <i>P</i> to <b>float</b> <i>v</i>
—	<b>setycomp</b> ( <i>P</i> , <i>v</i> )	set <i>y</i> component of <b>point</b> <i>P</i> to <b>float</b> <i>v</i>
—	<b>setzcomp</b> ( <i>P</i> , <i>v</i> )	set <i>z</i> component of <b>point</b> <i>P</i> to <b>float</b> <i>v</i>
float	<b>length</b> ( <i>V</i> )	return the Euclidean length of <b>point</b> <i>V</i>
float	<b>distance</b> ( <i>P1</i> , <i>P2</i> )	return the Euclidean length of ( <i>P1</i> – <i>P2</i> )
float	<b>area</b> ( <i>P</i> )	return the surface element area at <i>P</i> , in pixels
<b>point</b>	<b>normalize</b> ( <i>V</i> )	return <i>V</i> / <b>length</b> ( <i>V</i> ) for <b>point</b> <i>V</i>
<b>point</b>	<b>faceforward</b> ( <i>V</i> , <i>I</i> )	return <i>V</i> flipped to point opposite <i>I</i>
<b>point</b>	<b>reflect</b> ( <i>I</i> , <i>N</i> )	return reflection of incident ray <i>I</i> about normalized vector <i>N</i>
<b>point</b>	<b>refract</b> ( <i>I</i> , <i>N</i> , <i>eta</i> )	return incident ray <i>I</i> refracted through surface with normal <i>N</i> and index of refraction <b>float</b> <i>eta</i>
	<b>fresnel</b> ( <i>I</i> , <i>N</i> , <i>eta</i> , <i>Kr</i> , <i>Kt</i> [, <i>R</i> , <i>T</i> ] )	return reflectance coefficient <b>float</b> <i>Kr</i> , transmittance coefficient <b>float</b> <i>Kt</i> , reflected ray <i>R</i> , and refracted ray <i>T</i> , given incident ray <i>I</i> , surface normal <i>N</i> and relative index of refraction <b>float</b> <i>eta</i>
<b>point</b>	<b>transform</b> ( [ <i>fromspace</i> , ] <i>tospace</i> , <i>P</i> )	transform the <b>point</b> <i>P</i> from the coordinate system named by string <i>fromspace</i> to the coordinate space named by <i>tospace</i>
float	<b>depth</b> ( <i>P</i> )	return depth of <b>point</b> <i>P</i> in camera space, normalized between 0 at the near clipping plane and 1 at the far one
<b>point</b>	<b>calculatenormal</b> ( <i>P</i> )	return the normal to a surface at <b>point</b> <i>P</i>

Table 15.2 Geometric Shading Functions