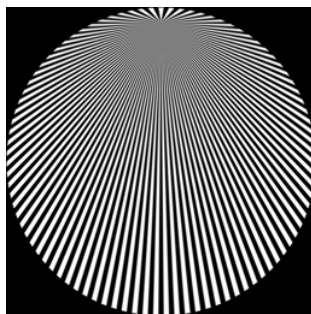


Sampling Theorem & Antialiasing

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Motivations

- “My ray traced images have a lot more pixels than the TV screen. Why do they look like @#\$%?”
- How to compute the pixel colors for the following pattern?



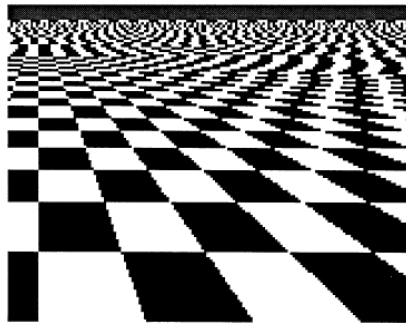
Antialiasing with Line Samples
Rendering Techniques '00 (Proceedings of
the 11th Eurographics Workshop on
Rendering), pp. 197-205
Thouis R. Jones, Ronald N. Perry

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Part I: Sampling Theorem

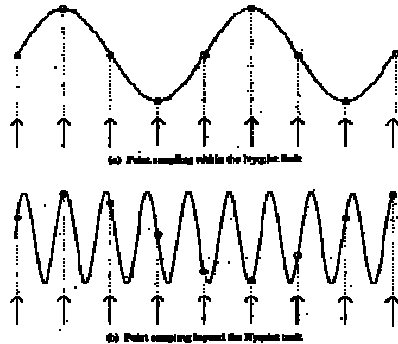
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Example of Aliasing in Computer Graphics



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Examples of Aliasing in 1D

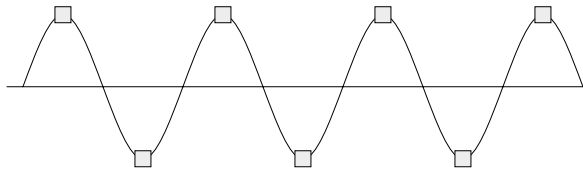


- See Figure 14.2 (p.394) of Watt's book for other examples.

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An Intuition – Using a Single Frequency

- It's easy to figure out for a sin wave.

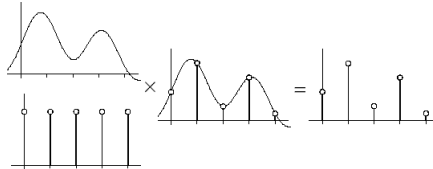


- What about any signal (usually a mixture of multiple frequencies)?
- Enter Fourier Transform...

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Sampling

- 1D Signal: $x \rightarrow f(x)$ becomes $i \rightarrow f(i)$

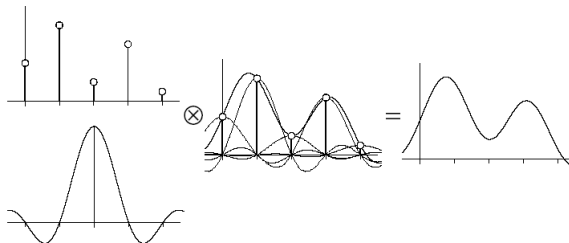


- 2D Image: $x, y \rightarrow f(x, y)$
 - For grayscale image, $f(x, y)$ is the intensity of pixel at (x, y) .

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Reconstruction

- If the samples are “dense” enough, then we can recover the original signal.

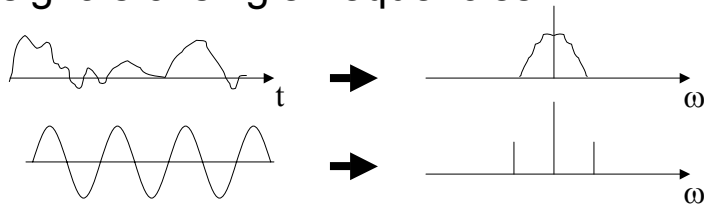


- Question is: How dense is enough?

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Fourier Transform

- Can we separate signal into a set of signals of single frequencies?



$$F(\omega) = \int_{-\infty}^{\infty} f(x)e^{-j\omega x} dx$$

$$e^{-j\omega x} = \cos \omega x + j \sin \omega x$$

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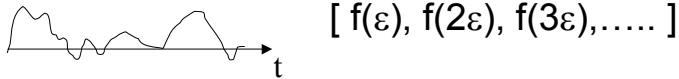
Basis Functions

- An example:
 $X = [x_1, x_2, \dots, x_n]$
 $U = [u_1, u_2, \dots, u_n]$
 $V = [v_1, v_2, \dots, v_n]$
Let $X = a \cdot U + b \cdot V$, how to find a and b?
- If U and V are orthogonal, then a and b are the projection of X onto U and V.

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Compared to Fourier Transform

- Consider a continuous signal as a infinite-dimensional vector



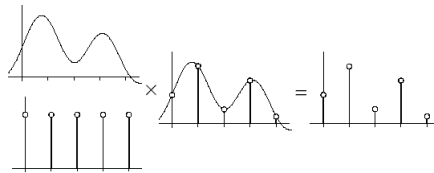
- Consider each frequency ω a basis, then $F(\omega)$ is the projection of $f(x)$ onto that basis.

$$F(\omega) = \int_{-\infty}^{\infty} f(x) e^{-j\omega x} dx$$

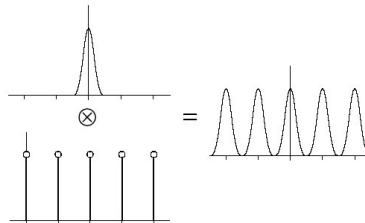
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Sampling

- Spatial domain:
multiply with a pulse train.



- Frequency domain:
convolution!



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Convolution

$$h(x) = f(x) \otimes g(x) = \int f(x')g(x - x')dx'$$

- To start with, imagine that $f(x)$ is nonzero only in the range of $[-a, a]$.
 - Then we only need to consider $g(x)$ in the range of $[x-a, x+a]$
- Multiplication in spatial domain results in convolution in frequency domain (and vice versa).

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An Intuition for Convolution

- Does it make sense to you that multiplication in one domain becomes convolution in the other domain?
- Look at this example:
$$P_1(x) = a_1x^3 + b_1x^2 + c_1x^1 + d_1$$
$$P_2(x) = a_2x^3 + b_2x^2 + c_2x^1 + d_2$$
- What are the coefficients of $P_1 * P_2$?

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- Consider $x^n, \dots, x^2, x^1, x^0$ as basis.

$$P_1(x) = a_1x^3 + b_1x^2 + c_1x^1 + d_1$$

$$P_2(x) = a_2x^3 + b_2x^2 + c_2x^1 + d_2$$

- Projections of P1 and P2 to the basis are (a_1, b_1, c_1, d_1) and (a_2, b_2, c_2, d_2)
- $P_1(x) \cdot P_2(x)$ results in: $(a_1, b_1, c_1, d_1) \otimes (a_2, b_2, c_2, d_2)$ in the transformed space.

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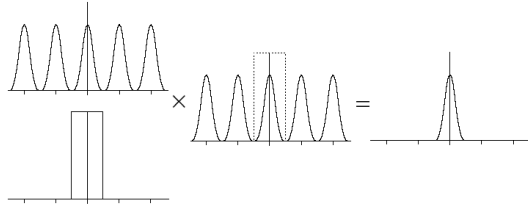
- The fact is: you have been doing convolution since elementary school!
- Example: $222 \cdot 111$ is computed as $(2,2,2) \otimes (1,1,1)$

$$\begin{array}{r}
 222 \times 111 = \\
 \\
 \\
 \\
 + \\
 \hline
 2 4 6 4 2
 \end{array}$$

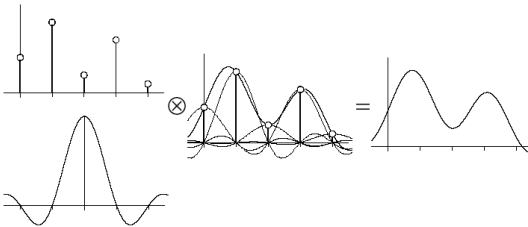
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Reconstruction

- Frequency domain:



- Spatial domain:
convolve with
Sinc function



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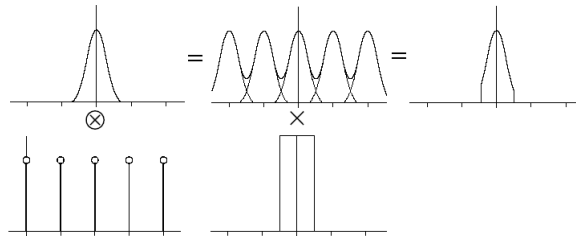
Reconstruction Kernel

- For perfect reconstruction, we need to convolve with the sinc function.
 - It's the Fourier transform of the box function.
 - It has infinite "support"
- May be approximated by Gaussian, cubic, or even triangle "tent" function.

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Nyquist Limit

- Nyquist Limit = $2 * \text{max_frequency}$
- Undersampling: sampling below the Nyquist Limit.



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Part II: Antialiasing

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Changes within a Pixel

- A lot can change within a pixel:

- Shading

- Edge

- Texture



- Point sampling at the center often produces undesirable result.

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Pixel Coverage

- What should be the pixel colors for these?



- Can we simply use the covered areas of blue and white? (Hint: convolve with box filter.)
- Do we have enough data to compute the coverage?

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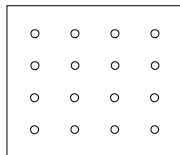
Antialiasing

- Consider a ray tracer. Is it often impossible to find the partial coverage of an edge.
- Each ray is a point sample.
- We may use many samples for each pixel → slower performance.

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Antialiasing – Uniform Sampling

- Also called supersampling



- Wasteful if not much changes within a pixel.

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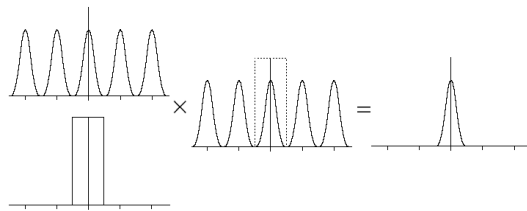
Filtering

- How do we reduce NxN supersamples into a pixel?
 - Average?
 - More weight near the center?
- Let's resort to the sampling theorem.

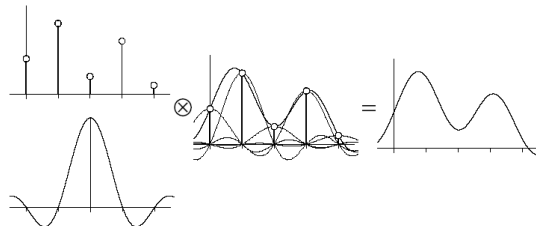
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Reconstruction

- Frequency domain:



- Spatial domain:



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A Few Observations

- In theory, a sample influences not only its pixel, but also every pixels in the image.
- What does it mean by removing high frequencies?

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Other Than Uniform Sampling?

- So far, the extra samples are taken uniformly in screen space.
- Other ways to take extra samples:
 - Adaptive sampling
 - Stochastic (or randomized) sampling

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Antialiasing – Adaptive Sampling

- Feasible in software, but difficult to implement in hardware.
- Increase samples only if necessary.
- But how do we know when is “necessary”?
 - Check the neighbors.

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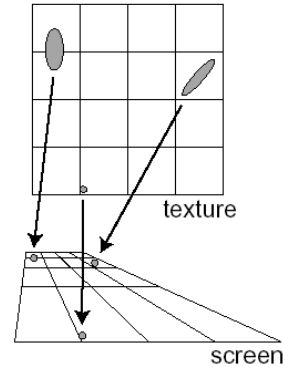
Antialiasing – Stochastic Sampling

- Keep the same number of samples per pixel.
- Replace the aliasing effects with noise that is easier to ignore.

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EWA for Texture Mapping

- Paul Heckbert, “Survey of Texture Mapping” IEEE CG&A, Nov. 1986. (Figures)
- Green & Heckbert, “Creating Raster Omnimax Images from Multiple Perspective Views Using The Elliptical Weighted Average Filter” IEEE CG&A, 6(6), pp. 21-27, June 1986.



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